Numerical relativity and sources of gravitational waves

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based on collaboration with
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Outline

- Introduction
- 2 A short review of 3+1 general relativity
- 3 A constrained scheme for 3+1 numerical relativity
- 4 Constraining the nuclear matter EOS from GW observations

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- York (1999): Conformal thin-sandwich (CTS) method for solving the constraint equations

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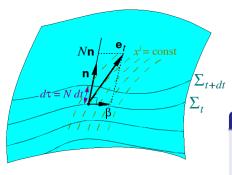
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3+1 decomposition of spacetime

Foliation of spacetime by a family of spacelike hypersurfaces $(\Sigma_t)_{t\in\mathbb{R}}$; on each hypersurface, pick a coordinate system $(x^i)_{i\in\{1,2,3\}}\Longrightarrow (x^\mu)_{\mu\in\{0,1,2,3\}}=(t,x^1,x^2,x^3)=$ coordinate system on spacetime



 $m{n}$: future directed unit normal to Σ_t : $m{n} = -N \, \mathbf{d}t, \, N$: lapse function $m{e}_t = \partial/\partial t$: time vector of the natural basis associated with the coordinates (x^μ)

$$\left\{egin{array}{ll} N: ext{ lapse function} \ \Sigma_{t+dt} & oldsymbol{eta}: ext{ shift vector} \end{array}
ight\} oldsymbol{e}_t = Noldsymbol{n} + oldsymbol{eta}$$

Geometry of the hypersurfaces Σ_t :

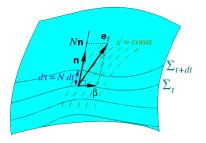
- induced metric $oldsymbol{\gamma} = oldsymbol{g} + oldsymbol{n} \otimes oldsymbol{n}$
- extrinsic curvature : $K = -\frac{1}{2}\mathcal{L}_n \gamma$

$$g_{\mu\nu} dx^{\mu} dx^{\nu} = -N^2 dt^2 + \gamma_{ij} \left(dx^i + \beta^i dt \right) \left(dx^j + \beta^j dt \right)$$

Choice of coordinates within the 3+1 formalism

$$(x^{\mu}) = (t, x^{i}) = (t, x^{1}, x^{2}, x^{3})$$

Choice of the lapse function $N \iff$ choice of the slicing (Σ_t) Choice of the shift vector $\boldsymbol{\beta} \iff$ choice of the spatial coordinates (x^i) on each hypersurface Σ_t



A well-spread choice of slicing: maximal slicing: $K := \operatorname{tr} K = 0$

[Lichnerowicz 1944]



3+1 decomposition of Einstein equation

Orthogonal projection of Einstein equation onto Σ_t and along the normal to Σ_t :

- Hamiltonian constraint: $R + K^2 K_{ij}K^{ij} = 16\pi E$
- Momentum constraint : $D_j K^{ij} D^i K = 8\pi J^i$
- Dynamical equations : $\frac{\partial K_{ij}}{\partial t} \mathcal{L}_{\beta} K_{ij} = \\ -D_i D_j N + N \left[R_{ij} 2K_{ik} K^k_{\ \ i} + KK_{ij} + 4\pi ((S-E)\gamma_{ij} 2S_{ij}) \right]$

$$E:=\boldsymbol{T}(\boldsymbol{n},\boldsymbol{n})=T_{\mu\nu}\,n^{\mu}n^{\nu}, \quad J_{i}:=-\gamma_{i}^{\ \mu}T_{\mu\nu}\,n^{\nu}, \quad S_{ij}:=\gamma_{i}^{\ \mu}\gamma_{j}^{\ \nu}T_{\mu\nu}, \quad S:=S_{i}^{\ i}$$

$$D_{i}: \text{ covariant derivative associated with }\boldsymbol{\gamma}, \quad R_{ij}: \text{ Ricci tensor of }D_{i}, \quad R:=R_{i}^{\ i}$$

 D_i : covariant derivative associated with γ , R_{ij} : Ricci tensor of D_i , $R:=R_i$ Kinematical relation between γ and K: $\frac{\partial \gamma^{ij}}{\partial t} + D^i \beta^j + D^j \beta^i = 2NK^{ij}$

Resolution of Einstein equation

Cauchy problem

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Free vs. constrained evolution in 3+1 numerical relativity

Einstein equations split into

dynamical equations $\frac{\partial}{\partial t}K_{ij}=\dots$ Hamiltonian constraint $R+K^2-K_{ij}K^{ij}=16\pi E$ momentum constraint $D_i K_i^{\ j} - D_i K = 8\pi J_i$

- 2-D computations(80's and 90's):
 - partially constrained schemes: Bardeen & Piran (1983), Stark & Piran (1985), Evans (1986)
 - fully constrained schemes: Evans (1989), Shapiro & Teukolsky (1992), Abrahams et al. (1994)
- 3-D computations (from mid 90's): Almost all based on free evolution schemes: BSSN, symmetric hyperbolic formulations, etc...
 - ⇒ problem: exponential growth of constraint violating modes

"Standard issue" $oldsymbol{1}$:

The constraints usually involve elliptic equations and 3-D elliptic solvers are CPU-time expensive!

Numerical relativity

Cartesian vs. spherical coordinates in 3+1 numerical relativity

- 1-D and 2-D computations: massive usage of spherical coordinates (r, θ, φ)
- 3-D computations: almost all based on Cartesian coordinates (x, y, z), although spherical coordinates are better suited to study objects with spherical topology (black holes, neutron stars). Two exceptions:
 - Nakamura et al. (1987): evolution of pure gravitational wave spacetimes in spherical coordinates (but with Cartesian components of tensor fields)
 - Stark (1989): attempt to compute 3D stellar collapse in spherical coordinates

"Standard issue" 2 :

Spherical coordinates are singular at r=0 and $\theta=0$ or π !

"Standard issues" 1 and 2 can be overcome

"Standard issues" 1 and 2 are neither mathematical nor physical

they are technical ones

⇒ they can be overcome with appropriate techniques

Spectral methods allow for

- an automatic treatment of the singularities of spherical coordinates (issue 2)
- fast 3-D elliptic solvers in spherical coordinates: 3-D Poisson equation reduced to a system of 1-D algebraic equations with banded matrices

[Grandclément, Bonazzola, Gourgoulhon & Marck, J. Comp. Phys. 170, 231 (2001)] (issue 1)

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A new scheme for 3+1 numerical relativity

Constrained scheme built upon maximal slicing and Dirac gauge

[Bonazzola, Gourgoulhon, Grandclément & Novak, PRD 70, 104007 (2004)]

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Conformal metric and dynamics of the gravitational field

Dynamical degrees of freedom of the gravitational field:

York (1972): they are carried by the conformal "metric"

$$\hat{\gamma}_{ij} := \gamma^{-1/3} \gamma_{ij}$$
 with $\gamma := \det \gamma_{ij}$

 $\hat{\gamma}_{ij} = tensor density of weight -2/3$

To work with tensor fields only, introduce an extra structure on Σ_t : a flat metric

$$f$$
 such that $rac{\partial f_{ij}}{\partial t}=0$ and $\gamma_{ij}\sim f_{ij}$ at spatial infinity (asymptotic flatness)

Define
$$\tilde{\gamma}_{ij} := \Psi^{-4} \gamma_{ij}$$
 or $\gamma_{ij} =: \Psi^{4} \tilde{\gamma}_{ij}$ with $\Psi := \left(\frac{\gamma}{f}\right)^{1/12}$, $f := \det f_{ij}$ $\tilde{\gamma}_{ij}$ is invariant under any conformal transformation of γ_{ij} and verifies $\det \tilde{\gamma}_{ij} = f$

Notations:
$$\tilde{\gamma}^{ij}$$
: inverse conformal metric : $\tilde{\gamma}_{ik} \tilde{\gamma}^{kj} = \delta_{ij}^{j}$

 \tilde{D}_i : covariant derivative associated with $\tilde{\gamma}_{ij}$, $\tilde{D}^i := \tilde{\gamma}^{ij} \tilde{D}_i$

 \mathcal{D}_i : covariant derivative associated with f_{ij} , $\mathcal{D}^i := f^{ij}\mathcal{D}_i$

Dirac gauge: definition

Conformal decomposition of the metric γ_{ij} of the spacelike hypersurfaces Σ_t :

$$\gamma_{ij} =: \Psi^4 \, \tilde{\gamma}_{ij} \qquad ext{with} \qquad \tilde{\gamma}^{ij} =: f^{ij} + h^{ij}$$

where f_{ij} is a flat metric on Σ_t , h^{ij} a symmetric tensor and Ψ a scalar field defined by $\Psi:=\left(\frac{\det\gamma_{ij}}{\det f_{ii}}\right)^{1/12}$

Dirac gauge (Dirac, 1959) = divergence-free condition on $\tilde{\gamma}^{ij}$:

$$\mathcal{D}_{j}\tilde{\gamma}^{ij}=\mathcal{D}_{j}h^{ij}=0$$

where \mathcal{D}_j denotes the covariant derivative with respect to the flat metric f_{ij} . Compare

- minimal distortion (Smarr & York 1978) : $D_j \left(\partial \tilde{\gamma}^{ij} / \partial t \right) = 0$
- ullet pseudo-minimal distortion (Nakamura 1994) : $\mathcal{D}^{j}\left(\partial ilde{\gamma}^{ij}/\partial t
 ight)=0$

Notice: Dirac gauge \iff BSSN connection functions vanish: $\tilde{\Gamma}^i = 0$

Dirac gauge: motivation

Expressing the Ricci tensor of conformal metric as a second order operator: In terms of the covariant derivative \mathcal{D}_i associated with the flat metric f:

$$ilde{\gamma}^{ik} ilde{\gamma}^{jl} ilde{R}_{kl} = rac{1}{2}\left(ilde{\gamma}^{kl}\mathcal{D}_k\mathcal{D}_lh^{ij} - ilde{\gamma}^{ik}\mathcal{D}_kH^j - ilde{\gamma}^{jk}\mathcal{D}_kH^i
ight) + \mathcal{Q}(ilde{\gamma}, \mathcal{D} ilde{\gamma})$$

with
$$H^i:=\mathcal{D}_jh^{ij}=\mathcal{D}_j\tilde{\gamma}^{ij}=-\tilde{\gamma}^{kl}\Delta^i_{\ kl}=-\tilde{\gamma}^{kl}(\tilde{\Gamma}^i_{\ kl}-\bar{\Gamma}^i_{\ kl})$$

and $\mathcal{Q}(\tilde{\gamma}, \mathcal{D}\tilde{\gamma})$ is quadratic in first order derivatives $\mathcal{D}h$ Dirac gauge: $H^i = 0 \Longrightarrow$ Ricci tensor becomes an elliptic operator for h^{ij} Similar property as harmonic coordinates for the 4-dimensional Ricci tensor:

$${}^4R_{\alpha\beta} = -\frac{1}{2}g^{\mu\nu}\frac{\partial}{\partial x^{\mu}}\frac{\partial}{\partial x^{\nu}}g_{\alpha\beta} + \text{quadratic terms}$$

Dirac gauge: discussion

• introduced by Dirac (1959) in order to fix the coordinates in some Hamiltonian formulation of general relativity; originally defined for Cartesian coordinates only: $\frac{\partial}{\partial x^j} \left(\gamma^{1/3} \, \gamma^{ij} \right) = 0$

but trivially extended by us to more general type of coordinates (e.g. spherical) thanks to the introduction of the flat metric f_{ij} :

$$\mathcal{D}_j\left((\gamma/f)^{1/3}\gamma^{ij}\right) = 0$$

- first discussed in the context of numerical relativity by Smarr & York (1978), as a candidate for a radiation gauge, but disregarded for not being covariant under coordinate transformation $(x^i) \mapsto (x^{i'})$ in the hypersurface Σ_t , contrary to the *minimal distortion gauge* proposed by them
- fully specifies (up to some boundary conditions) the coordinates in each hypersurface Σ_t , including the initial one \Rightarrow allows for the search for stationary solutions

Dirac gauge: discussion (con't)

- leads asymptotically to transverse-traceless (TT) coordinates (same as minimal distortion gauge). Both gauges are analogous to Coulomb gauge in electrodynamics
- turns the Ricci tensor of conformal metric $\tilde{\gamma}_{ij}$ into an elliptic operator for h^{ij} \Longrightarrow the dynamical Einstein equations become a wave equation for h^{ij}
- ullet results in a vector elliptic equation for the shift vector eta^i

Maximal slicing + Dirac gauge

Our choice of coordinates to solve numerically the Cauchy problem:

- choice of Σ_t foliation: maximal slicing: $K := \operatorname{tr} K = 0$
- choice of (x^i) coordinates within Σ_t : Dirac gauge: $\mathcal{D}_i h^{ij} = 0$

Note: the Cauchy problem has been shown to be locally strongly well posed for a similar coordinate system, namely constant mean curvature (K=t) and spatial harmonic coordinates $\left(\mathcal{D}_j\left[\left(\gamma/f\right)^{1/2}\gamma^{ij}\right]=0\right)$ [Andersson & Moncrief, Ann. Henri Poincaré 4, 1 (2003)]

3+1 Einstein equations in maximal slicing + Dirac gauge

[Bonazzola, Gourgoulhon, Grandclément & Novak, PRD 70, 104007 (2004)]

• 5 elliptic equations (4 constraints + K = 0 condition) ($\Delta := \mathcal{D}_k \mathcal{D}^k$):

$$\Delta N = \Psi^4 N \left[4\pi (E+S) + \tilde{A}_{kl} A^{kl} \right] - h^{kl} \mathcal{D}_k \mathcal{D}_l N - 2 \tilde{D}_k \ln \Psi \, \tilde{D}^k N$$

$$\begin{split} \Delta(\Psi^2 N) &= \Psi^6 N \left(4\pi S + \frac{3}{4} \tilde{A}_{kl} A^{kl} \right) - h^{kl} \mathcal{D}_k \mathcal{D}_l(\Psi^2 N) \\ &+ \Psi^2 \left[N \left(\frac{1}{16} \tilde{\gamma}^{kl} \mathcal{D}_k h^{ij} \mathcal{D}_l \tilde{\gamma}_{ij} - \frac{1}{8} \tilde{\gamma}^{kl} \mathcal{D}_k h^{ij} \mathcal{D}_j \tilde{\gamma}_{il} \right. \\ &+ 2 \tilde{D}_k \ln \Psi \, \tilde{D}^k \ln \Psi \right) + 2 \tilde{D}_k \ln \Psi \, \tilde{D}^k N \bigg]. \end{split}$$

$$\Delta \beta^{i} + \frac{1}{3} \mathcal{D}^{i} \left(\mathcal{D}_{j} \beta^{j} \right) = 2A^{ij} \mathcal{D}_{j} N + 16\pi N \Psi^{4} J^{i} - 12N A^{ij} \mathcal{D}_{j} \ln \Psi$$
$$-2\Delta^{i}_{kl} N A^{kl} - h^{kl} \mathcal{D}_{k} \mathcal{D}_{l} \beta^{i} - \frac{1}{3} h^{ik} \mathcal{D}_{k} \mathcal{D}_{l} \beta^{l}$$

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3+1 equations in maximal slicing + Dirac gauge (cont'd)

• 2 scalar wave equations for two scalar potentials χ and μ :

$$\begin{split} &-\frac{\partial^2 \chi}{\partial t^2} + \Delta \chi = S_\chi \\ &-\frac{\partial^2 \mu}{\partial t^2} + \Delta \mu = S_\mu \end{split}$$

The remaining 3 degrees of freedom are fixed by the Dirac gauge:

From the two potentials χ and μ , construct a TT tensor \bar{h}^{ij} according to the formulas (components with respect to a spherical f-orthonormal frame)

$$\bar{h}^{rr} = \frac{\chi}{r^2}, \ \, \bar{h}^{r\theta} = \frac{1}{r} \left(\frac{\partial \eta}{\partial \theta} - \frac{1}{\sin \theta} \frac{\partial \mu}{\partial \phi} \right), \ \, \bar{h}^{r\phi} = \frac{1}{r} \left(\frac{1}{\sin \theta} \frac{\partial \eta}{\partial \phi} + \frac{\partial \mu}{\partial \theta} \right), \ \, \text{etc...}$$

with
$$\Delta_{\theta\phi}\eta = -\partial\chi/\partial r - \chi/r$$

Numerical implementation

Numerical code based on the C++ library LORENE (http://www.lorene.obspm.fr) with the following main features:

- multidomain spectral methods based on spherical coordinates (r, θ, φ) , with compactified external domain (\Longrightarrow spatial infinity included in the computational domain for elliptic equations)
- very efficient outgoing-wave boundary conditions, ensuring that all modes with spherical harmonics indices $\ell=0,\ \ell=1$ and $\ell=2$ are perfectly outgoing [Novak & Bonazzola, J. Comp. Phys. 197, 186 (2004)] (recall: Sommerfeld boundary condition works only for $\ell=0$, which is too low for gravitational waves)

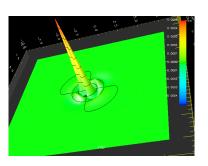
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Results on a pure gravitational wave spacetime

Initial data: similar to [Baumgarte & Shapiro, PRD **59**, 024007 (1998)], namely a momentarily static $(\partial \tilde{\gamma}^{ij}/\partial t = 0)$ Teukolsky wave $\ell = 2$, m = 2:

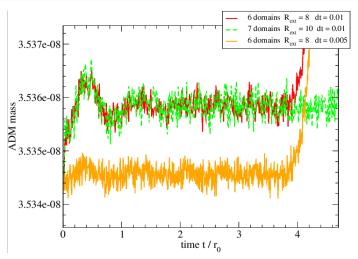
$$\begin{cases} \chi(t=0) &=& \frac{\chi_0}{2} \, r^2 \exp\left(-\frac{r^2}{r_0^2}\right) \sin^2\theta \, \sin2\varphi \\ \mu(t=0) &=& 0 \end{cases}$$
 with $\chi_0=10^{-3}$

Preparation of the initial data by means of the conformal thin sandwich procedure



Evolution of $h^{\phi\phi}$ in the plane $\theta=\frac{\pi}{2}$

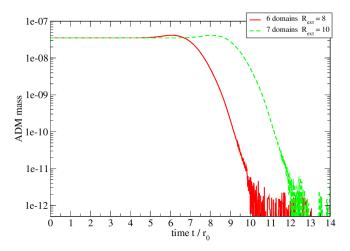
Test: conservation of the ADM mass



Number of coefficients in each domain: $N_r=17$, $N_\theta=9$, $N_\varphi=8$ For $dt=5\,10^{-3}r_0$, the ADM mass is conserved within a relative error lower than 10^{-4}

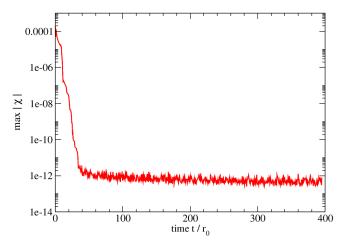
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Late time evolution of the ADM mass



At $t > 10 r_0$, the wave has completely left the computation domain \implies Minkowski spacetime

Long term stability



Nothing happens until the run is switched off at $t=400\,r_0$!

Summary

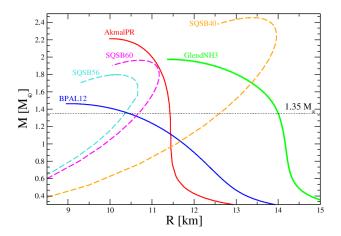
- Dirac gauge + maximal slicing reduces the Einstein equations into a system of
 - two scalar elliptic equations (including the Hamiltonian constraint)
 - one vector elliptic equations (the momentum constraint)
 - two scalar wave equations (evolving the two dynamical degrees of freedom of the gravitational field)
- The usage of spherical coordinates and spherical components of tensor fields is crucial in reducing the dynamical Einstein equations to two scalar wave equations
- The unimodular character of the conformal metric ($\det \tilde{\gamma}_{ij} = \det f_{ij}$) is ensured in our scheme
- First numerical results show that Dirac gauge + maximal slicing seems a promising choice for stable evolutions of 3+1 Einstein equations and gravitational wave extraction
- It remains to be tested on black hole spacetimes !



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Our current poor knowledge of nuclear matter EOS



Constraining the nuclear matter EOS from GW observations of binary coalescence

Methods based on the merger or post-merger signal:

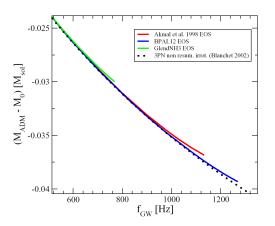
- Measure of the radius from the shape of the GW spectrum in a coalescing BH-NS system [Saijo & Nakamura, PRL 85, 2665 (2000)]
- Constraining the EOS softness from the post-merger signal in binary NS coalescence (prompt black formation vs. supramassive NS remnant)

[Shibata, Taniguchi & Uryu, PRD 71, 084021 (2005)] [Shibata, PRL 94, 201101 (2005)]

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Constraining the nuclear matter EOS from GW observations of the inspiral phase

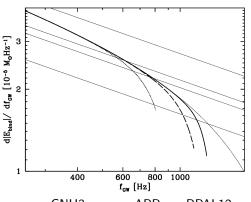
Evolutionary sequences of irrotational binary NS:



[Bejger, Gondek-Rosińska, Gourgoulhon, Haensel, Taniguchi & Zdunik, A&A 431, 297 (2005)]

Constraining the nuclear matter EOS from GW observations of the inspiral phase

GW energy spectrum

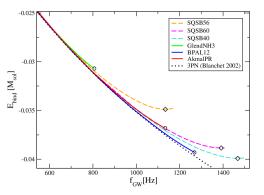


...... GNH3, --- APR, — BPAL12

[Bejger, Gondek-Rosińska, Gourgoulhon, Haensel, Taniguchi & Zdunik, A&A 431, 297 (2005)]

Determining the nuclear matter EOS from GW observations

Evolutionary sequences of irrotational binary strange stars:



[Limousin, Gondek-Rosińska & Gourgoulhon, PRD 71, 064012 (2005)]

[Gondek-Rosińska, Bejger, Bulik, Gourgoulhon, Haensel, Limousin & Zdunik, preprint: gr-qc/0412010)]