GR computations with the Python-based free computer algebra system SageMath

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- no need to learn any specific syntax to use it
- Python is a very powerful object oriented language, with a neat syntax
- SageMath benefits from the Python ecosystem (e.g. Jupyter notebook)

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SageMath is developed by an enthusiastic community

- mostly composed of mathematicians
- welcoming newcomers

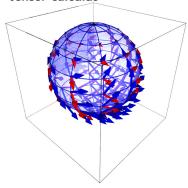
Tensor calculus with SageMath

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SageManifolds project: extends SageMath towards differential geometry and tensor calculus



- https://sagemanifolds.obspm.fr
- fully included in SageMath
- ~ 15 contributors (developers and reviewers)
 cf. https://sagemanifolds.obspm.fr/
 authors.html
- dedicated mailing list
- help: https://ask.sagemath.org

Stereographic-coordinate frame on \mathbb{S}^2

Everybody is very welcome to contribute

visit https://sagemanifolds.obspm.fr/contrib.html

Current status

Already present (SageMath 8.8):

- differentiable manifolds: tangent spaces, vector frames, tensor fields, curves, pullback and pushforward operators, submanifolds
- standard tensor calculus (tensor product, contraction, symmetrization, etc.), even on non-parallelizable manifolds, and with all monoterm tensor symmetries taken into account
- Lie derivatives of tensor fields
- differential forms: exterior and interior products, exterior derivative, Hodge duality
- multivector fields: exterior and interior products, Schouten-Nijenhuis bracket
- affine connections (curvature, torsion)
- pseudo-Riemannian metrics
- computation of geodesics (numerical integration)

Current status

Already present (cont'd):

- some plotting capabilities (charts, points, curves, vector fields)
- parallelization (on tensor components) of CPU demanding computations
- extrinsic geometry of pseudo-Riemannian submanifolds
- tensor series expansions

Future prospects:

- more symbolic backends (Giac, FriCAS, ...)
- more graphical outputs
- symplectic forms, fibre bundles, spinors, integrals on submanifolds, variational calculus, etc.
- connection with numerical relativity: use SageMath to explore numerically-generated spacetimes

A short example:

Near-horizon geometry of the extremal Kerr black hole

This notebook derives the near-horizon geometry of the extremal (i.e. maximally spinning) Kerr black hole. It is based on SageMath tools developed through the SageManifolds project.

First we set up the notebook to display maths using LaTeX rendering and to perform computations in parallel on 8 threads:

```
In [1]: %display latex
Parallelism().set(nproc=8)
```

Spacetime manifold

We declare the Kerr spacetime (or more precisely the part of it covered by Boyer-Lindquist coordinates) as a 4-dimensional Lorentzian manifold \mathcal{M} :

```
In [2]: M = Manifold(4, 'M', latex_name=r'\mathcal{M}', structure='Lorentzian')
print(M)
```

4-dimensional Lorentzian manifold M

We then introduce the standard **Boyer-Lindquist coordinates** (t, r, θ, ϕ) as a chart BL (for *Boyer-Lindquist*) on \mathcal{M} :

```
In [3]: BL.<t,r,th,ph> = M.chart(r"t r th:(0,pi):\theta ph:(0,2*pi):periodic:\phi")
print(BL); BL
Chart (M, (t, r, th, ph))
```

```
Out[3]: (\mathcal{M}, (t, r, \theta, \phi))
```

Metric tensor of the extremal Kerr spacetime

In [4]: m = var('m', domain='real')

Out[5]: Ric(g) = 0

The metric is set by its components in the coordinate frame associated with Boyer-Lindquist coordinates, which is the current manifold's default frame:

$$\begin{array}{l} \mathbf{a} = \mathbf{m} & \# \ \text{extremal Kerr} \\ \text{rho2} = \mathbf{r}^2 + (\mathbf{a}^* \cos(\mathsf{th})) \cap 2 \\ \text{Delta} = \mathbf{r}^* - 2 - 2^* \mathbf{m}^* \mathbf{r} + \mathbf{a}^* - 2 \\ \mathbf{g} = \mathbf{M}. \mathsf{metric}() \\ \mathbf{g}[\theta, \theta] = -(1 - 2^* \mathbf{m}^* \mathbf{r}' \mathbf{r} \mathsf{ho2}) \\ \mathbf{g}[\theta, 3] = -2^* \mathbf{a}^* \mathbf{m}^* \mathbf{r}' \mathbf{s} \mathsf{in}(\mathsf{th}) \wedge 2 / \mathsf{rho2} \\ \mathbf{g}[1, 1], \ \mathbf{g}[2, 2] = \mathsf{rho2} / \mathsf{Delta}, \ \mathsf{rho2} \\ \mathbf{g}[3, 3] = (\mathbf{r}^2 + \mathbf{a}^2 + 2^* \mathbf{m}^* \mathbf{r}^* \mathbf{s} \mathsf{in}(\mathsf{th})) \wedge 2 / \mathsf{rho2}) * \mathbf{sin}(\mathsf{th}) \wedge 2 \\ \mathbf{g}. & \text{display}() \\ \\ \mathbf{g} = \left(\frac{2mr}{m^2 \cos(\theta)^2 + r^2} - 1\right) \mathsf{d}t \otimes \mathsf{d}t + \left(-\frac{2m^2 r \sin(\theta)^2}{m^2 \cos(\theta)^2 + r^2}\right) \mathsf{d}t \otimes \mathsf{d}\phi + \left(\frac{m^2 \cos(\theta)^2 + r^2}{m^2 - 2mr + r^2}\right) \mathsf{d}r \otimes \mathsf{d}r \\ & + \left(m^2 \cos(\theta)^2 + r^2\right) \mathsf{d}\theta \otimes \mathsf{d}\theta + \left(-\frac{2m^2 r \sin(\theta)^2}{m^2 \cos(\theta)^2 + r^2}\right) \mathsf{d}\phi \otimes \mathsf{d}t + \left(\frac{2m^3 r \sin(\theta)^2}{m^2 \cos(\theta)^2 + r^2} + m^2 + r^2\right) \sin(\theta)^2 \mathsf{d}\phi \\ & \otimes \mathsf{d}\phi \\ \end{array}$$

Check that we are dealing with a solution of the vacuum Einstein equation:

```
In [5]: g.ricci().display()
```

Near-horizon coordinates

Let us introduce the chart NH of the near-horizon coordinates $(\bar{t}, \bar{r}, \theta, \bar{\phi})$:

In [6]: NH.<tb,rb,th,phb> = M.chart(r"tb:\bar{t} rb:\bar{r} th:(0,pi):\theta phb:(0,2*pi):periodic:\
 print(NH)
 NH

Chart (M, (tb, rb, th, phb))

Out[6]:
$$(\mathcal{M}, (\bar{t}, \bar{r}, \theta, \bar{\phi}))$$

Following J. Bardeen and G. T. Horowitz, Phys. Rev. D 60, 104030 (1999), the near-horizon coordinates $(\bar{t},\bar{r},\theta,\bar{\phi})$ are related to the Boyer-Lindquist coordinates by

$$\bar{t} = \epsilon t, \quad \bar{r} = \frac{r - m}{\epsilon}, \quad \theta = \theta, \quad \bar{\phi} = \phi - \frac{t}{2m},$$

where ϵ is a constant parameter. The horizon of the extremal Kerr black hole is located at r=m, which corresponds to $\bar{r}=0$

We implement the above relations as a transition map from the chart BL to the chart NH:

- In [7]:
 eps = var('eps', latex_name=r'\epsilon')
 BL_to_NH = BL.transition_map(NH, [eps*t, (r-m)/eps, th, ph t/(2*m)])
 BL_to_NH.display()
- Out[7]: $\begin{cases} \bar{t} = \epsilon t \\ \bar{r} = -\frac{m-r}{\epsilon} \\ \theta = \theta \\ \bar{\phi} = \phi \frac{t}{2m} \end{cases}$

In [8]: BL_to_NH.inverse().display()

Out[8]:
$$\begin{cases} t = \frac{\bar{t}}{\epsilon} \\ r = \epsilon \bar{r} + m \\ \theta = \theta \\ \phi = \frac{2 \epsilon m \bar{\phi} + \bar{t}}{\epsilon} \end{cases}$$

The metric components with respect the coordinates $(\bar{t}, \bar{r}, \theta, \bar{\phi})$ are computed by passing the chart NH to the method display():

$$\begin{aligned} & \text{Out} \text{[9]:} \\ & g = \left(-\frac{m^2 \bar{r}^2 \cos{(\theta)^4} - \epsilon^2 \bar{r}^4 - 4 \, \epsilon m \bar{r}^3 - 3 \, m^2 \bar{r}^2 + \left(\epsilon^2 \bar{r}^4 + 4 \, \epsilon m \bar{r}^3 + 6 \, m^2 \bar{r}^2 \right) \cos{(\theta)^2}}{4 \, \left(\epsilon^2 m^2 \bar{r}^2 + m^4 \cos{(\theta)^2} + 2 \, \epsilon m^3 \bar{r} + m^4 \right)} \right) \mathrm{d}\bar{t} \otimes \mathrm{d}\bar{t} \\ & + \left(-\frac{\epsilon m^2 \bar{r}^2 \sin{(\theta)^4} - \left(\epsilon^3 \bar{r}^4 + 4 \, \epsilon^2 m \bar{r}^3 + 8 \, \epsilon m^2 \bar{r}^2 + 4 \, m^3 \bar{r} \right) \sin{(\theta)^2}}{2 \, \left(\epsilon^2 m \bar{r}^2 + m^3 \cos{(\theta)^2} + 2 \, \epsilon m \bar{r} + m^3 \right)} \right) \mathrm{d}\bar{t} \otimes \mathrm{d}\bar{\phi} \\ & + \left(-\frac{\epsilon m^2 \bar{r}^2 \sin{(\theta)^4} - \left(\epsilon^3 \bar{r}^4 + 4 \, \epsilon^2 m \bar{r}^3 + 8 \, \epsilon m^2 \bar{r}^2 + 4 \, m^3 \bar{r} \right) \sin{(\theta)^2}}{\bar{r}^2} \right) \mathrm{d}\bar{\phi} \otimes \mathrm{d}\bar{t} \\ & + \left(-\frac{\epsilon m^2 \bar{r}^2 \sin{(\theta)^4} - \left(\epsilon^3 \bar{r}^4 + 4 \, \epsilon^2 m \bar{r}^3 + 8 \, \epsilon m^2 \bar{r}^2 + 4 \, m^3 \bar{r} \right) \sin{(\theta)^2}}{2 \, \left(\epsilon^2 m \bar{r}^2 + m^3 \cos{(\theta)^2} + 2 \, \epsilon m^2 \bar{r} + m^3 \right)} \right) \mathrm{d}\bar{\phi} \otimes \mathrm{d}\bar{t} \\ & + \left(-\frac{\epsilon^2 m^2 \bar{r}^2 \sin{(\theta)^4} - \left(\epsilon^4 \bar{r}^4 + 4 \, \epsilon^3 m \bar{r}^3 + 8 \, \epsilon^2 m^2 \bar{r}^2 + 8 \, \epsilon m^3 \bar{r} + 4 \, m^4 \right) \sin{(\theta)^2}}{\epsilon^2 \bar{r}^2 + m^2 \cos{(\theta)^2} + 2 \, \epsilon m \bar{r} + m^2} \right) \mathrm{d}\bar{\phi} \otimes \mathrm{d}\bar{\phi} \end{aligned}$$

From now on, we use the near-horizon coordinates as the default ones on the spacetime manifold:

```
In [10]: M.set_default_chart(NH)
M.set_default_frame(NH.frame())
```

The near-horizon metric h as the limit $\epsilon \to 0$ of the Kerr metric g

Let us define the *near-horizon metric* as the metric h on $\mathcal M$ that is the limit $\epsilon \to 0$ of the Kerr metric g. The limit is taken by asking for a series expansion of g with respect to ϵ up to the 0-th order (i.e. keeping only ϵ^0 terms). This is acheived via the method truncate:

$$\begin{aligned} \text{Out} & [\textbf{11}] : \\ h &= \left(-\frac{\bar{r}^2 \cos{(\theta)^4} + 6\,\bar{r}^2 \cos{(\theta)^2} - 3\,\bar{r}^2}{4\left(m^2 \cos{(\theta)^2} + m^2\right)} \right) \mathrm{d}\bar{r} \otimes \mathrm{d}\bar{r} + \left(\frac{2\,\bar{r}\sin{(\theta)^2}}{\cos{(\theta)^2} + 1} \right) \mathrm{d}\bar{r} \otimes \mathrm{d}\bar{\phi} + \left(\frac{m^2 \cos{(\theta)^2} + m^2}{\bar{r}^2} \right) \mathrm{d}\bar{r} \otimes \mathrm{d}\bar{r} \\ &+ \left(m^2 \cos{(\theta)^2} + m^2 \right) \mathrm{d}\theta \otimes \mathrm{d}\theta + \left(\frac{2\,\bar{r}\sin{(\theta)^2}}{\cos{(\theta^2 + 1)}} \right) \mathrm{d}\bar{\phi} \otimes \mathrm{d}\bar{r} + \left(\frac{4\,m^2 \sin{(\theta)^2}}{\cos{(\theta^2 + 1)}} \right) \mathrm{d}\bar{\phi} \otimes \mathrm{d}\bar{\phi} \end{aligned}$$

We note that the metric h is not asymptotically flat.

Killing vectors of the near-horizon geometry

Let us first consider the vector field $\eta:=\frac{\partial}{\partial \bar{\phi}}$:

It is a Killing vector of the near-horizon metric, since the Lie derivative of h along η vanishes:

```
In [13]: h.lie_derivative(eta).display()
```

Out[13]: 0

This is not surprising since the components of h are independent from $\bar{\phi}$.

Similarly, we can check that $\xi_1:=rac{\partial}{\partial t}$ is a Killing vector of h, reflecting the independence of the components of h from \bar{t} :

```
In [14]: xi1 = M.vector_field(1, 0, 0, 0, name='xi2', latex_name=r'\xi_{1}')

xi1.display()

Out[14]: \xi_1 = \frac{\partial}{\partial x_1}
```

```
In [15]: h.lie_derivative(xi1).display()
```

Out[15]: 0

The above two Killing vectors correspond respectively to the **axisymmetry** and the **pseudo-stationarity** of the Kerr metric. A third symmetry, which is not present in the original Kerr metric, is the invariance under the **scaling** $(\bar{t}, \bar{r}) \mapsto (\alpha \bar{t}, \bar{r}/\alpha)$, as it is clear on the metric components in Out[11]. The corresponding Killing vector is

Out[16]:
$$\xi_2 = \bar{t} \frac{\partial}{\partial \bar{t}} - \bar{r} \frac{\partial}{\partial \bar{r}}$$

Out[17]: 0

Finally, a fourth Killing vector is

Out[18]:
$$\xi_3 = \left(\frac{2m^4}{\bar{r}^2} + \frac{1}{2}\bar{t}^2\right)\frac{\partial}{\partial\bar{t}} - \bar{r}\bar{t}\frac{\partial}{\partial\bar{r}} - \frac{2m^2}{\bar{r}}\frac{\partial}{\partial\bar{\phi}}$$

Out[19]: 0

Symmetry group

We have four independent Killing vectors, η , ξ_1 , ξ_2 and ξ_3 , which implies that the symmetry group of the near-horizon geometry is a 4-dimensional Lie group G. Let us determine G by investigating the **structure constants** of the basis $(\eta, \xi_1, \xi_2, \xi_3)$ of the Lie algebra of G. First of all, we notice that η commutes with the other Killing vectors:

- In [20]: for xi in [xi1, xi2, xi3]:
 show(eta.bracket(xi).display())
 - $[\eta, \xi_1] = 0$
 - $[\eta, \xi_2] = 0$
 - $[\eta, \xi_3] = 0$

Since η generates the rotation group SO(2)=U(1), we may write that $G=U(1)\times G_3$, where G_3 is a 3-dimensional Lie group, whose generators are (ξ_1,ξ_2,ξ_3) . Let us determine the structure constants of these three vectors. We have

- In [21]: xi1.bracket(xi2).display()
- Out[21]: $[\xi_1, \xi_2] = \frac{\partial}{\partial \bar{t}}$
- In [22]: xi1.bracket(xi3).display()
- Out[22]: $[\xi_1, \xi_3] = \bar{t} \frac{\partial}{\partial \bar{t}} \bar{r} \frac{\partial}{\partial \bar{r}}$
- In [23]: xi2.bracket(xi3).display()
- Out[23]: $[\xi_2, \xi_3] = \left(\frac{4 \, m^4 + \bar{r}^2 \bar{t}^2}{2 \, \bar{r}^2}\right) \frac{\partial}{\partial \bar{t}} \bar{r} \bar{t} \frac{\partial}{\partial \bar{r}} \frac{2 \, m^2}{\bar{r}} \frac{\partial}{\partial \bar{\phi}}$

To summarize, we have

Out[24]: True

To recognize a standard Lie algebra, let us perform a slight change of basis:

```
In [25]: vE = -sqrt(2)*xi3
vF = sqrt(2)*xi1
vH = 2*xi2
```

We have then the following commutation relations:

Out[26]: True

We recognize the Lie algebra $\mathfrak{Sl}(2,\mathbb{R})$. Indeed, we have

Out[27]: True

$$Lie(G_3) = \mathfrak{gl}(2, \mathbb{R}).$$

At this stage, G_3 could be $SL(2,\mathbb{R})$, $PSL(2,\mathbb{R})$ or $SL(2,\mathbb{R})$ (the universal covering group of $SL(2,\mathbb{R})$). One can show that actually $G_3 = SL(2,\mathbb{R})$. We conclude that the full isometry group of the near-horizon geometry is $G = U(1) \times SL(2,\mathbb{R})$.

The full notebook is available at

https://nbviewer.jupyter.org/github/sagemanifolds/SageManifolds/blob/master/Notebooks/SM_extremal_Kerr_near_horizon.ipynb



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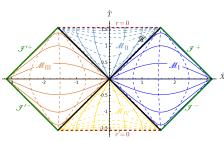
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Many other examples are posted at https://sagemanifolds.obspm.fr/examples.html

Carter-Penrose diagram computed and drawn with SageMath \rightarrow



Want to join the project or simply to stay tuned?

visit https://sagemanifolds.obspm.fr/ (download, documentation, example notebooks, mailing list)