xPand: An algorithm for perturbing homogeneous cosmologies

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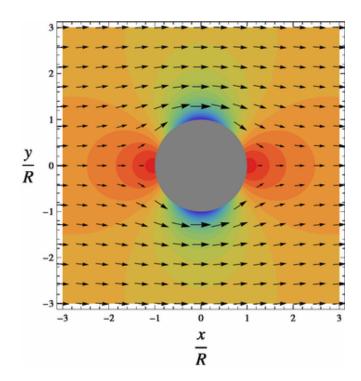
Outline

- 1) Tensor fields in physics.
- 2) Tensor algebra package. Why and how? presentation of xAct
- 3) Cosmological perturbations.
- 4) Implementation in *xPand*

Tensor fields

All classical and continuous physics is expressed in terms of *tensor fields* on a *manifold*. Well known examples are

-Fluid dynamics (Pressure P, Energy density ρ , velocity \vec{V} -Electromagnetism $\vec{E} \ \vec{B}$ fields, but also $V \& \vec{A}$)

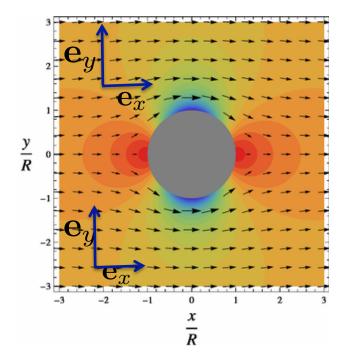


Manifold, coordinates, and vector basis

In general the mathematical structure is obvious and hidden

- The manifold is flat and trivial : $\,\mathbb{R}^3\,$ and time is a parameter
- Natural coordinates are (x,y,z) or (r,ϑ,ϕ) or (r,ϑ,z) This labels the point we are considering
- Natural basis

$$\mathbf{e}_1 = \frac{\partial}{\partial x} = (1, 0, 0)$$



Temperature T(x,y,z)

Velocity (components) $v^{x}(x,y,z), v^{y}(x,y,z), v^{z}(x,y,z)$

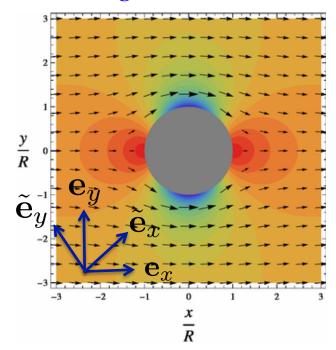
Vector basis and forms basis

We need a set of 1-forms to get the components of a vector. Indeed a form associates a number to a vector

The co-basis is a set of forms e^{i} i =1,2,3 (or i=x,y,z)

$$\mathbf{e}^{i}[\mathbf{e}_{j}] = \delta^{i}_{j} \quad \Rightarrow \mathbf{e}^{i}[\mathbf{V}] = \mathbf{e}^{i}[V^{k}\mathbf{e}_{k}] = V^{i}$$

Change of basis



$$\tilde{\mathbf{e}}_i = \mathbf{e}_i R^j{}_i$$
 Co-variance

$$\mathbf{e}^i = R^i{}_j \tilde{\mathbf{e}}^j$$
 Contra-variance

A vector field is defined, independently from the basis used to measure its components. It has a pure geometrical meaning

$$\mathbf{V} = V^i \mathbf{e}_i = \tilde{V}^i \tilde{\mathbf{e}}_i$$

Examples of tensors

We define the object

$$\mathbf{R} = R^i{}_j \mathbf{e}_i \otimes \mathbf{e}^j$$

$$\tilde{\mathbf{e}}_j = \mathbf{R}[\mathbf{e}_j] = \mathbf{e}_i R^i{}_j$$

So very naturally, the quantities which appear in equations are more general than just scalar fields and vector yields.

But it appears more natural to work with coordinates.

e.g. In fluid dynamics we have the strain rate, which comes from differences of velocity inside the fluid

$$\sigma = \sigma_{ij} \mathbf{e}^i \otimes \mathbf{e}^j \qquad \qquad \sigma_{ij} = \partial_i v_j + \partial_j v_i$$

and the stress tensor $\Sigma = \Sigma_{ij} \mathbf{e}^i \otimes \mathbf{e}^j$ which enters the Navier-Stokes

$$\Sigma = \mu[\sigma] \qquad \qquad \Sigma_{ij} = \mu_{ij}^{kl} \sigma_{kl}$$

Measuring the components of the viscosity tensor μ is the program of rheology

Adapted notation for tensors

- 1) We want to keep the geometrical meaning Relations are valid for any basis We can specify to Cartesian or spherical coordinates only at the very end
- 2) When a tensor is applied to another tensor and is of complicated nature like μ we need to keep track of what 1-form is applied to which vector

The solution is to use *abstract indices* which are only here to remember the tensorial nature

- We can contract indices (apply a form to a vector)
$$A^{ijk}B_{kl}$$

- We can take the tensor product of two tensors $v^i v^j$
- We can build new tensors with (covariant) derivatives $abla_i v_j$
- We can specify some symmetries, antisymmetries $T_{ij}-T_{ji}$

Usually we use a different set of indices to avoid confusion a,b,c instead of i,j,k for instance or Greek letters.

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So why an abstract tensor calculus

- 1) Expressions can become quite large in the derivation manipulation of equations space! We use the RAM
- 2) Simplifications can be complicated and take a very long time time! We use the CPU

Specifications we need:

Input

- -a notation for up and down abstract indices
- -contraction of indices (Einstein convention of summation)
- -covariant derivatives
- -a metric and an inverse metric to raise or lower indices. Not necessarily flat.

Output

- -A simplification routines which detects terms which are equivalent
- -Nice display with indices placed in the correct position (up&down)

Several packages available: I know only *xAct* ... http://www.xact.es/

Especially for cosmological perturbations...

- 1) The large scale structure of the universe is very close to a homogeneous and isotropic solution.
- 2) The growth of structure is understood as the result of gravitationnal collapse of small fluctuations around this idealized background
- 3) Linearizing the theory of gravity (GR for the standard model) is the easiest -it accounts very well for the growth of structure on large and intermediary scales -it is rather computationally involved to get the equations due to the complexity of GR
- 4) Non-linear theory is needed to account for small scales (non-linear) effects
 -non-Gaussianity induced by non-linear effects?
 -GR effects in the N-body simulations?

The derivation of equations can take a very long time and is rather tedious

Loading the package xAct

```
In[1]:= << xAct/xTensor.m
    Package xAct'xPerm' version 1.2.0, {2013, 1, 27}
    CopyRight (C) 2003-2013, Jose M. Martin-Garcia, under the General Public License.
    Connecting to external mac executable...
    Connection established.
    Package xAct'xTensor' version 1.0.5. (2013. 3. 3)
    CopyRight (C) 2002-2013 Jose M. Martin-Garcia, under the General Public License.
    These packages come with ABSOLUTELY NO WARRANTY; for details type
      Disclaimer[]. This is free software, and you are welcome to redistribute
      it under certain conditions. See the General Public License for details.
 ln[2]:= DefManifold[M4, 4, {a, b, c, d, e, f, g, h}]
     ** DefManifold: Defining manifold M4.
     ** DefVBundle: Defining vbundle TangentM4.
 In[3]:= DefMetric[-1, metric[-a, -b], CD]
     ** DefTensor: Defining symmetric metric tensor metric[-a, -b].
     ** DefTensor: Defining antisymmetric tensor epsilonmetric[-a, -b, -c, -d].
     ** DefTensor: Defining tetrametric Tetrametric[-a, -b, -c, -d].
     ** DefTensor: Defining tetrametric Tetrametrict[-a, -b, -c, -d].
```

.. Deficer. Defining committee designative CD[al

Basic syntax

 \rightarrow ln[10]:= CD[-a]@v[-b]

Out[10]= Va Vh

```
__in[4]:= DefTensor[v[a], M4]
      DefTensor[T[a, b], M4]
      ** DefTensor: Defining tensor v[a].
      ** DefTensor: Defining tensor T[a, b].
 ln[6] := T[-a, b] v[-b]
Out[6]= Tab Vb
 ln[7] = T[-a, b] v[-b] + T[-a, -b] v[b] - 2 metric[b, c] v[-c] T[-a, -b]
Out[7]= Tab Vb + Tab Vb - 2 metricbc Tab Vc
→In[8]:= ContractMetric[%]
Out[8]= T_a^b V_b - T_{ab} V^b

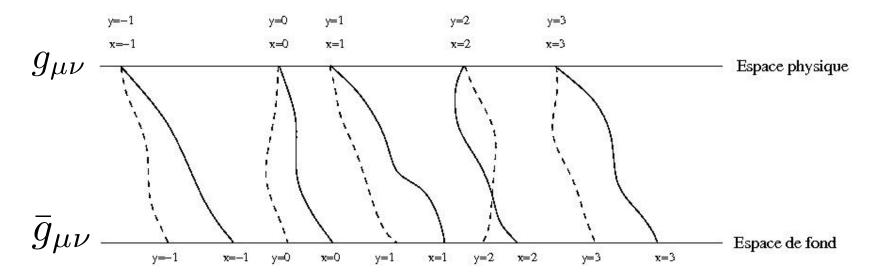
Nn[9]:= ToCanonical [%]

Out[9] = 0
```

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- 3) Cosmological perturbations.How to do perturbations in generalHow to do cosmological perturbations in particular
- 4) Implementation in *xPand*

Cosmological perturbations in General



Perturbations are tensorial fields, living on the background spacetime. They can be decomposed in orders of perturbations

$$\phi^*[g_{\mu\nu}] - \bar{g}_{\mu\nu} \equiv \Delta[g_{\mu\nu}]$$

$$\Delta[g_{\mu\nu}] = \sum_{n=1}^{\infty} \frac{{}^{(n)}h_{\mu\nu}}{n!}$$

Cosmological Perturbations in General

Perturbation of the inverse metric
$$\frac{1}{1+x} = 1 - x + x^2 - x^3 \dots$$

$$\Delta^n \left[\left(\bar{g}^{-1} \right)^{\mu \nu} \right] = \sum_{(k_i)} (-1)^m \frac{n!}{k_1! \dots k_m!} \, {}^{\{k_m\}} h^{\mu \zeta_m - \{k_{m-1}\}} h_{\zeta_m}^{-\zeta_{m-1}} \, \dots \, {}^{\{k_2\}} h_{\zeta_3}^{-\zeta_2 - \{k_1\}} h_{\zeta_2}^{-\nu} \, ,$$

Perturbation of the Christoffel

$$\begin{split} \Delta^n \left[\bar{\Gamma}^\rho_{\ \mu\nu} \right] = & \sum_{(k,\cdot)} (-1)^{m+1} \frac{n!}{k_1! \dots k_m!} \, ^{\{k_m\}} h^{\rho \zeta_m - \{k_{m-1}\}} h_{\zeta_m}^{\ \zeta_{m-1}} \ \dots \ ^{\{k_2\}} h_{\zeta_3}^{\ \zeta_2 - \{k_1\}} h_{\zeta_2 \mu\nu} \,, \\ ^{\{n\}} h_{\rho\mu\nu} = & \frac{1}{2} \left(\bar{\nabla}_\nu \, ^{\{n\}} h_{\rho\mu} + \bar{\nabla}_\mu \, ^{\{n\}} h_{\rho\nu} - \bar{\nabla}_\rho \, ^{\{n\}} h_{\mu\nu} \right) \,. \end{split}$$

Perturbation of the Riemann tensor

$$\Delta^{n} \left[\bar{R}_{\mu\nu\rho}{}^{\sigma} \right] = \bar{\nabla}_{\nu} \left(\Delta^{n} \left[\bar{\Gamma}^{\sigma}{}_{\mu\rho} \right] \right) - \sum_{i=1}^{n-1} \binom{n}{k} \Delta^{k} \left[\bar{\Gamma}^{\zeta}{}_{\nu\rho} \right] \Delta^{n-k} \left[\bar{\Gamma}^{\sigma}{}_{\zeta\mu} \right] - (\mu \leftrightarrow \nu),$$

All perturbations of geometrical tensors are expressed in function of the perturbed metric and its background covariant derivative

$$(n)h_{\mu\nu}$$
 $\bar{\nabla}_{\alpha}^{(n)}h_{\mu\nu}$ $\bar{\nabla}_{\alpha}\bar{\nabla}_{\beta}^{(n)}h_{\mu\nu}$

General perturbations: using xPert (D. Brizuela et al 2006-now)

```
In[f]:= << xAct'xPert'
    Package xAct'xPerm' version 1.2.0, {2013, 1, 27}
    CopyRight (C) 2003-2013, Jose M. Martin-Garcia, under the General Public License.
    Connecting to external mac executable...
    Connection established.
    Package xAct'xTensor' version 1.0.5, {2013, 3, 3}
    CopyRight (C) 2002-2013, Jose M. Martin-Garcia, under the General Public License.
ln[2] = DefManifold[M, 4, {\alpha, \beta, \mu, \nu, \lambda, \sigma}]
      DefMetric [-1, g[-\alpha, -\beta], CD, \{";", "\nabla"\}, PrintAs \rightarrow "\overline{g}"];
      ** DefManifold: Defining manifold M.
      ** DefVBundle: Defining vbundle TangentM.
      ** DefTensor: Defining symmetric metric tensor g[-\alpha, -\beta].
      ** DefTensor: Defining antisymmetric tensor epsilong [-\alpha, -\beta, -\lambda, -\mu].
      ** DefTensor: Defining tetrametric Tetrag[-\alpha, -\beta, -\lambda, -\mu].
      ** DefTensor: Defining tetrametric Tetrag† [-\alpha, -\beta, -\lambda, -\mu].
      ** DefCovD: Defining covariant derivative CD[-\alpha].
 In[4]:= DefMetricPerturbation[q, dq, €];
        ** DefParameter: Defining parameter €.
        ** DefTensor: Defining tensor dg[LI[order], -α, -β].
In[5]:= ExpandPerturbation@Perturbed[RicciScalarCD[], 1] // ContractMetric // ToCanonical
Out[5]= -\epsilon \operatorname{dg}^{1\alpha\beta} R[\nabla]_{\alpha\beta} + R[\nabla] + \epsilon \operatorname{dg}^{1\alpha\beta}_{\alpha\beta} = \epsilon \operatorname{dg}^{1\alpha}_{\alpha\beta}^{\beta},
```

Cosmological Perturbations.

When cosmologists write the simplest perturbed metric, they write

$$ds^{2} = a(\eta)^{2} [-(1+2\Phi)d\eta^{2}) + (1-2\Psi)\gamma_{ij}dx^{i}dx^{j}]$$

What they mean

$$\phi^*[g_{\mu\nu}] - \bar{g}_{\mu\nu} = a^2[-2\Phi d\eta \otimes d\eta - 2\Psi \gamma_{ij} dx^j \otimes dx^j]$$

Roadmap:

- -Find the general expression for a perturbed tensor (perturbation of Einstein tensor typically)
- -Perform a conformal transformation to account for the scale factor
- -Restrict to a given order (first order for simplicity)
- -Replace the general first order metric perturbation by its parameterization?
- -Read the result?

Φ

 Ψ

Conformal transformation

```
In[7]:= Conformal[g, ga2] [RiemannCD[-\alpha, -\beta, -\mu, \nu]]

** DefTensor: Defining tensor ChristoffelCDCDa2[\alpha, -\beta, -\lambda].

Out[7]= R[\nabla] _{\alpha\beta\mu}^{\ \ \nu} - \frac{\delta_{\beta}^{\ \ \nu}}{(a)^2} \frac{g_{\alpha\mu}}{(a)^2} \frac{(\nabla_{\lambda}a)}{(a)^2} + \frac{\delta_{\alpha}^{\ \ \nu}}{(a)^2} \frac{g_{\beta\mu}}{(a)^2} \frac{(\nabla_{\lambda}a)}{(a)^2} + \frac{2\delta_{\beta}^{\ \ \nu}}{(a)^2} \frac{(\nabla_{\alpha}a)}{(a)^2} \frac{(\nabla_{\mu}a)}{(a)^2} - \frac{2\delta_{\beta}^{\ \ \nu}}{(a)^2} \frac{(\nabla_{\alpha}a)}{(a)^2} \frac{(\nabla^{\nu}a)}{(a)^2} + \frac{2\delta_{\beta}^{\ \ \nu}}{(a)^2} \frac{(\nabla_{\alpha}a)}{(a)^2} \frac{(\nabla^{\nu}a)}{(a)^2} + \frac{2\delta_{\beta\mu}}{(a)^2} \frac{(\nabla^{\nu}\nabla_{\alpha}a)}{(a)^2} - \frac{2\delta_{\beta\mu}}{(a)^2} \frac{(\nabla^{\nu}\nabla_{\alpha}a)}{(a)^2} \frac{(\nabla^{\nu}a)}{(a)^2} \frac{(\nabla^{\nu
```

Roadmap

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Reading the result: 1+3 splitting of background

See Eric Gourgoulhon's review on 1+3/ADM

The background cosmological solution (Friedmann-Lemaître):

- -The expansion is contained entirely in the scale factor $\,\tilde{\bar{g}}_{\mu\nu}=a^2\bar{g}_{\mu\nu}$
- -A class of free falling observers define the cosmic time \bar{n}^{μ}
- -The spatial sections have (conformal) metric $\bar{h}_{\mu\nu} = \bar{g}_{\mu\nu} + \bar{n}_{\mu}\bar{n}_{\nu}$
- -The spatial sections are homogeneous (invariant under translation),

This means that we have a natural 1+3 slicing of the background manifold

-The scale factor contains all the extrinsic curvature of the slicing. $\bar{\nabla}_{\mu}\bar{n}_{\nu}=0$

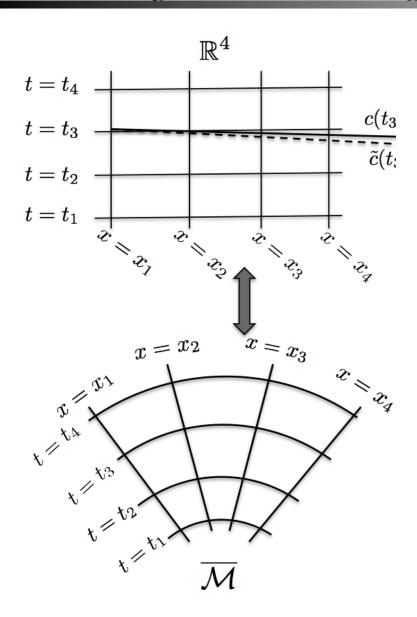
 $\bar{n}^{\mu}\bar{\nabla}_{\mu}\bar{n}_{\nu}=0$

- -There is no acceleration of the vector normal to the slices
- -The curvature of the spatial section is the curvature of $\bar{h}_{\mu\nu}$ Gauss-Codacci relates ${}^4\bar{R}_{\alpha\beta\mu\nu}$ to ${}^3\bar{R}_{\alpha\beta\mu\nu}$

$${}^{3}\bar{R}_{\mu\nu\rho\sigma} = 2k\,\bar{h}_{\rho[\mu}\,\bar{h}_{\nu]\sigma}\,, \qquad {}^{3}\bar{R}_{\mu\nu} = 2k\,\bar{h}_{\mu\nu}\,, \qquad {}^{3}\bar{R} = 6k$$

$$\tilde{\bar{g}}_{\mu\nu} = a^2 \bar{g}_{\mu\nu} \qquad \bar{g}_{\mu\nu} = -\bar{n}_{\mu} \otimes \bar{n}_{\nu} + \bar{h}_{\mu\nu} \qquad {}^3 \bar{R}_{\alpha\beta\mu\nu}$$

1+3 Background slicing made visual



Parameterisation of the perturbed metric

So when the parameterisation of the perturbed metric is

$$a^{2}[-2\Phi d\eta \otimes d\eta - 2\Psi \gamma_{ij} dx^{j} \otimes dx^{j}]$$

we replace the first order perturbed metric by

$$^{(1)}g_{\mu\nu} = -2\Phi \bar{n}_{\mu}\bar{n}_{\nu} - 2\Psi \bar{h}_{\mu\nu}$$

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Splitting perturbation equation

The equations obtained by hand (Einstein equations) are typically of the form

$$\Phi'' + \frac{a'}{a}\Phi' + \partial_i\partial^i\Psi = 0$$

What is the geometrical meaning of

- Time derivative ? Answer : $\mathcal{L}_{\bar{n}}\Phi = \Phi'$
- Partial derivative ? Answer: an induced covariant derivative

$$D_{\mu}\Phi \equiv h^{\nu}_{\mu}\nabla_{\nu}\Phi$$

$$\nabla_{\mu}\Phi = -\bar{n}^{\mu}\mathcal{L}_{\bar{n}}\Phi + D_{\mu}\Phi$$

$$\mathcal{L}_{\bar{n}}^2 \Phi + \frac{a'}{a} \mathcal{L}_{\bar{n}} \Phi + D_{\mu} D^{\mu} \Phi = 0$$

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 How to do perturbations in general

 How to do cosmological perturbations in particular
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Examples of Implementation in xPand

http://www2.iap.fr/users/pitrou/xpand.htm

```
In[1]:= << xAct/xPand.m;</pre>
    Package xAct'xPerm' version 1.2.0, {2013, 1, 27}
    CopyRight (C) 2003-2013, Jose M. Martin-Garcia, under the General Public License.
     Connecting to external mac executable...
     Connection catablished
ln[2]:= DefManifold[M, 4, {\alpha, \beta, \mu, \nu}];
     DefMetric[-1, g[-\alpha, -\beta], CD, {";", "\nabla"}];
     ** DefManifold: Defining manifold M.
     ** DefVBundle: Defining vbundle TangentM.
     ** DefTensor: Defining symmetric metric tensor g[-α, -β].
     ** DefTensor: Defining antisymmetric tensor epsilong [-\alpha, -\beta, -\mu, -\nu].
     ** DefTensor: Defining tetrametric Tetrag[-\alpha, -\beta, -\mu, -\nu].
  In[4]:= DefMetricPerturbation[g, dg, ε];
       ** DefParameter: Defining parameter ε.
       ** DefTensor: Defining tensor dg[LI[order], -\alpha, -\beta].
  In[5]:= SetSlicing[g, n, h, cd, {"|", "D"}, "FLCurved"];
        ** DefTensor: Defining tensor n[v$1095].
        ** DefTensor: Defining symmetric metric tensor h[-v$1095, -v$1096].
        ** DefTensor: Defining antisymmetric tensor epsilonh [-\alpha, -\beta, -\mu].
         Define and Defining total metals metals ( )
```

Examples of Implementation in xPand

```
In[6]:= order = 1;
        DefProjectedTensor[φ[], h];
        DefProjectedTensor[\psi[], h];
         ** DefTensor: Defining tensor
          φ[LI[xAct`xPand`Private`p$3488], LI[xAct`xPand`Private`q$3488]].
         ** DefTensor: Defining tensor
          MyRicciScalar =
      ExpandPerturbation@Perturbed[Conformal[g, gah2][RicciScalarCD[]], order]
    ** DefTensor: Defining tensor ChristoffelCDCDah2 [\alpha, -\beta, -\mu].
  = \frac{R[\nabla]}{\left(a\right)^{2}} - \frac{6\nabla_{\alpha}\nabla^{\alpha}a}{\left(a\right)^{3}} + \varepsilon \left[ -\frac{6\left(-dg^{1\alpha\beta}\nabla_{\alpha}\nabla_{\beta}a - \frac{1}{2}g^{\alpha\beta}\nabla_{\mu}a\left(\nabla_{\alpha}dg^{1\mu}_{\beta} + \nabla_{\beta}dg^{1\mu}_{\alpha} - \nabla^{\mu}dg^{1}_{\alpha\beta}\right)\right)}{\left(a\right)^{3}} + \frac{1}{\left(a\right)^{2}}\right]
             \left(-dg^{1\vee\vee1} R[\nabla]_{\vee\vee1} + g^{\vee\vee1} \left(\frac{1}{2} \left(-\nabla_{\nu}\nabla_{\nu1}dg^{1\vee2}_{\nu2} - \nabla_{\nu}\nabla_{\nu2}dg^{1\vee2}_{\nu1} + \nabla_{\nu}\nabla^{\vee2}dg^{1}_{\nu1\vee2}\right) + \right)\right)
                        \frac{1}{2} \left( \nabla_{v2} \nabla_{v} dg^{1v2}_{v1} + \nabla_{v2} \nabla_{v1} dg^{1v2}_{v} - \nabla_{v2} \nabla^{v2} dg^{1}_{v1v} \right) \right)
```

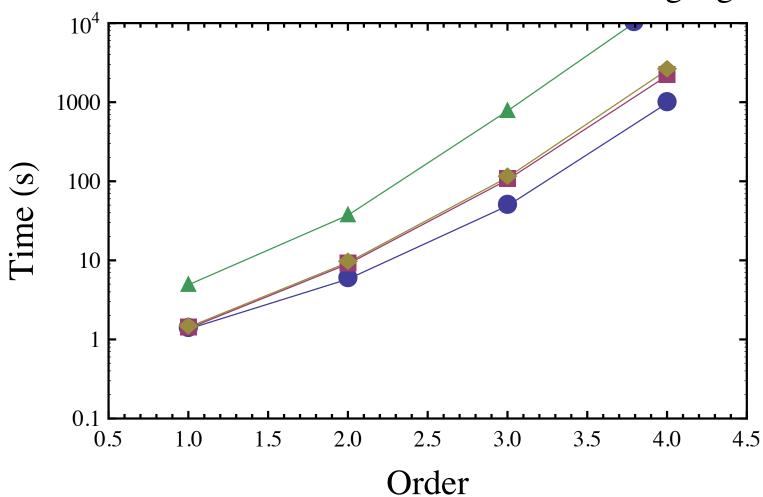
Examples of Implementation in xPand

```
In[10]:= MyGauge =  \{ dg[LI[order], \alpha_{-}, \beta_{-}] \Rightarrow -2 n[\alpha] n[\beta] \varphi[LI[order]] - 2 h[\alpha, \beta] \psi[LI[order]] \}; 
 + \frac{1}{\ln[12]:=} SplitPerturbations[ah[]^2 MyRicciScalar, MyGauge, h] 
The Splitting of a^2 + \dots was performed in 0.721687 seconds.

Out[12]= 6 \mathcal{H}^2 + 6 \mathcal{H} + 6 \mathcal{H} + 6 \mathcal{H} + \epsilon \left(-12 \mathcal{H}^2 \binom{(1)}{\varphi} - 12 \mathcal{H} \binom{(1)}{\varphi} - 6 \mathcal{H} \binom{(1)}{\varphi} + 12 \mathcal{H} \binom{(1)}{\psi} - 18 \mathcal{H} \binom{(1)}{\psi} - 6 \binom{(1)}{\psi} - 2 \binom{(1)}{\psi} - 2 \binom{(1)}{\psi} + 4 \binom{(1)}{\psi} + 4 \binom{(1)}{\psi} + 4 \binom{(1)}{\psi} - 4 \binom{(1)}
```

Benchmarking





More subtle details if there is time

-We have non scalar perturbations B_{μ}, E_{μ} $H_{\mu
u}$

$$\bar{\nabla}_{\rho} T_{\mu_1...\mu_p} = -\bar{n}_{\rho} \mathcal{L}_{\bar{n}} T_{\mu_1...\mu_p} + \bar{D}_{\rho} T_{\mu_1...\mu_p} + 2 \sum_{i=1}^{p} \bar{n}_{(\mu_i} \bar{K}^{\sigma}_{\ \rho)} T_{\mu_1...\mu_{i-1}\sigma\mu_{i+1}...\mu_p}.$$

-General equations are second order. We need to commute induced derivatives and spatial derivatives (time and space derivative).

$$\mathcal{L}_{\bar{\boldsymbol{n}}}\left(\bar{D}_{\rho}T_{\mu_{1}...\mu_{p}}\right) = \bar{D}_{\rho}\left(\mathcal{L}_{\bar{\boldsymbol{n}}}T_{\mu_{1}...\mu_{p}}\right) + \sum_{i=1}^{p}\left(\bar{h}^{\sigma\zeta}\bar{D}_{\zeta}\bar{K}_{\rho\mu_{i}} - \bar{D}_{\rho}\bar{K}_{\mu_{i}}^{\phantom{\mu_{i}}\sigma} - \bar{D}_{\mu_{i}}\bar{K}_{\rho}^{\sigma}\right)T_{\mu_{1}...\mu_{i-1}\sigma\mu_{i+1}...\mu_{p}},$$

-Can be extended to anisotropic spacetimes. Extrinsic curvature non-vanishing (symmetric trace-free part) $\bar{
abla}_{\mu}\bar{n}_{\nu}=\sigma_{\mu\nu}$ Meaning of homogeneity from Killing vector fields

-Perturbation of fluids require to ensure the norm of relativistic velocity is -1. Only three degrees of freedom.

Conclusion

- -General method. Can be implemented in any package for abstract tensor manipulations
- -Easily extended to homogenous bu anisotropic spacetimes Bianchi spaces (constants of structure and shear of expansion)
- -Fluid can be incorporated easily. The only subtlty is the constraint coming from the fixed norm of the relativistic velocity Conservation equation comes easily once this is done.
- -Need of a mode decomposition (from induced derivative to Fourier space)
- -Scalar field stress-energy tensor, multifluids
- -Fast. Goes easily up to orders which are anyway too high to be interesting numerically.
- -No need to start over all the derivation when changing the parameterisation of perturbations
- -Geodesic equation and deviation equation to be incorporated 1+3 -> 1+1+2

Thanks a lot for your attention