

Lecture 3 - PPN Framework1. Parametrize the metric

- effect of boosts

~~3 PPN~~ 6 PPN- preferred frame if $(\alpha_1, \alpha_2, \alpha_3)$ not all zero2. Conservation laws

A. Baryon number

$$(n u^\alpha)_{;\alpha} = 0$$

If mass per baryon is constant,

$$(\rho u^\alpha)_{;\alpha} = 0 = \frac{1}{\sqrt{-g}} (\sqrt{-g} \rho u^\alpha)_{;\alpha} = 0$$

$$\text{Define } \rho^* = \rho \sqrt{-g} u^0 \approx \rho \left(1 + \frac{1}{2} v^2 + 3\gamma U\right)$$

$$\frac{\partial \rho^*}{\partial t} + \nabla \cdot (\rho^* \underline{v}) = 0 \quad - \text{"conserved" density}$$

- exact

Note $\rho^* d^3x = \text{invariant} = \text{rest mass inside comoving volume}$ B. Cons. of energy

$$T^{\mu\nu}_{;\nu} = 0$$

$$T^{\mu\nu} = (\rho(1+\pi) + p) u^\mu u^\nu + p g^{\mu\nu}$$

$$u_\mu T^{\mu\nu}_{;\nu} = 0 = u^\mu (\rho + \rho\pi + p)_{;\nu} u^\mu u^\nu + (\rho + \rho\pi + p) (u_\mu u^\mu_{;\nu} u^\nu + u^\mu_{;\nu} u^\nu) + p_{;\mu} u^\mu$$

$$= -\frac{d}{dt} (\rho + \rho\pi) - (\rho + \rho\pi + p) \nabla \cdot u$$

Show that $\nabla \cdot u = \frac{1}{v} \frac{dv}{dt}$

$$v \frac{d}{dt} (\rho + p\pi) + (\rho + p\pi) \frac{dv}{dt} + p \frac{dv}{dt} = 0$$

$$\frac{d}{dt} [(\rho + p\pi)v] + p \frac{dv}{dt} = 0$$

$$dE + p dV = \delta Q = T dS = 0 \text{ [isentropic]}$$

C. Global Conservation laws

$$\begin{aligned} \text{In SET } T^{m\nu}_{; \nu} = 0 &\Rightarrow \int (T^{m0}_{; 0} + T^{mj}_{; j}) d^3x \\ &= \frac{\partial}{\partial t} \int T^{m0} d^3x + \oint T^{mj} d^2S_j \\ T^{m0} &= \text{const } (E, P) \quad \text{no flux} \end{aligned}$$

In Related E Eq. we had

$$T^{m\nu}_{; \nu} = 0 \Rightarrow \int T^{m0} d^3x = \text{const if no GW}$$

But $T^{m\nu}_{; \nu} = 0$ doesn't give cons. law because of Γ^i

In PPN: given $T^{m\nu}_{; \nu} = 0$ can we construct a

quantity $\tau^{m\nu} \sim (1 - aU) T^{m\nu} + t^{m\nu}$ such that

$$\begin{array}{l|l} T^{m\nu}_{; \nu} = 0 & \Rightarrow E, P \text{ conserved} \\ T^{m\nu} = T^{\nu\mu} & \Rightarrow J, CM. \end{array} \left| \begin{array}{l} \alpha_3 = \int_1^2 \int_3^4 = 0 \\ \alpha_1 = \alpha_2 = 0 \end{array} \right.$$

eg NGT

3. Equations of Motion - Photons

- postulate null geodesics

- can also prove from Maxwell's eqns

$$F^{MV}{}_{;V} = 0 \quad A^M{}_{;M} = 0 \quad \lambda \ll \{R, L\}$$

$$\boxed{\begin{aligned} k^\nu k^\mu{}_{;\nu} &= 0 \\ k^\mu k_\mu &= 0 \end{aligned}}$$

$$A^M = (Q^M + \delta B^M + \dots) e^{i\theta/\delta}$$

$$k^M = \frac{dx^M}{d\tau} \quad k_\mu = \theta_{,\mu}$$

τ affine param.

$$\frac{d^2 x^\mu}{d\tau^2} + \Gamma^\mu{}_{\alpha\beta} \frac{dx^\alpha}{d\tau} \frac{dx^\beta}{d\tau} = 0$$

use t as parameter, $x^0 = t$

$$\frac{d^2 t}{d\tau^2} + \Gamma^0{}_{\alpha\beta} \frac{dx^\alpha}{d\tau} \frac{dx^\beta}{d\tau} = 0$$

$$\Rightarrow \boxed{\begin{aligned} \frac{d^2 x^j}{dt^2} + \left(\Gamma^j{}_{\alpha\beta} - \Gamma^0{}_{\alpha\beta} \frac{dx^j}{dt} \right) \frac{dx^\alpha}{dt} \frac{dx^\beta}{dt} \\ g_{\mu\nu} \frac{dx^\mu}{dt} \frac{dx^\nu}{dt} = 0 \end{aligned}}$$

Subst

$$x^j = \hat{n}^j (t - t_0) + x_p^j(t)$$

$$\hat{n} \cdot \hat{n} = 1$$

$$\frac{d^2 x_p}{dt^2} = (1 + \gamma) (\nabla U - 2 \frac{\hat{n} \cdot \nabla U}{\hat{n}} \hat{n})$$

$$\hat{n} \cdot \frac{dx_p}{dt} = -(1 + \gamma) U$$

4. Equations of Motion - Bodies.

$$P^{\alpha}{}_{\mu} T^{\mu\nu}{}_{;\nu} = 0$$

$$= P^{\alpha}{}_{\mu} \left\{ (\rho + p) u^{\mu}{}_{;\nu} u^{\nu} \right.$$

$$\left. + (\rho + p) \underbrace{u^{\nu} u^{\mu}}_{a^{\mu}}{}_{;\nu} + (\rho + p) u^{\mu} u^{\nu}{}_{;\nu} + \rho_{;\nu} g^{\mu\nu} \right\}$$

Projection operator

$$P^{\alpha}{}_{\nu} = \delta^{\alpha}_{\nu} + u^{\alpha} u_{\nu}$$

$$P^{\mu}{}_{\nu} u^{\nu} = 0$$

$$\boxed{(\rho + p) a^{\alpha} = - P^{\alpha\mu} P_{;\mu}}$$

j component

$$a^j = \frac{d^2 x^j}{d\tau^2} + \Gamma^j_{\alpha\beta} u^{\alpha} u^{\beta}$$

$$v^{\alpha} = (1, \vec{v})$$

$$= \left(\frac{dt}{d\tau}\right)^2 \left[\frac{d^2 x^j}{dt^2} - \Gamma^j_{\alpha\beta} v^{\alpha} v^{\beta} \right]$$

$$\therefore \boxed{\frac{d^2 x^j}{dt^2} = -\Gamma^j_{\alpha\beta} v^{\alpha} v^{\beta} + \Gamma^0_{\alpha\beta} v^{\alpha} v^{\beta} v^j - \left(\frac{dt}{d\tau}\right)^2 \frac{P^{jk}}{\rho + p}}$$

Define a CM for each body

$$X_a^i = \frac{1}{m_a} \int_a \rho x^i d^3x$$

$$m_a = \int_a \rho d^3x$$

$$\text{or } X_a^i = \frac{1}{m_a} \int_a \rho^* x^i d^3x$$

$$m_a = \int_a \rho^* d^3x$$

$$\text{or } X^i = \frac{1}{M} \int \rho^* \left(1 + \frac{1}{2} \vec{v}^2 - \frac{1}{2} \bar{U} + \Pi\right) x^i d^3x \quad M = \int \rho^* d^3x$$

$$\frac{dX_a^i}{dt} = \frac{d}{dt} \left\{ \frac{1}{m_a} \left(p_a^i \right) x_a^i dx^3 \right\}$$

Result

PPT

$$\underline{a}_a = (a_a)_{\text{SELF}} + (a_a)_{\text{NEWT}} + (a_a)_{\text{NOBODY}}$$

Self terms

6 terms eg. $t^i = \int \rho \rho' \frac{v^i (x-x')^i}{|x-x'|^3} d^3x$

- all depend on J_1, J_2, J_3, J_4, K_3 - vanish in conservative theory.

"Newtonian"

- for spherical bodies

$$(a_a)^i_{\text{NEWT}} = \sum_b \frac{1}{m_a} (m_p)_a \left(\sum_{b \neq a} \frac{(m_A)_b}{r_{ab}} \right) v^i$$

[NGT: $m = m_p = m_A$]

PPT

$$\frac{(m_p)_a}{m_a} = 1 - \left(4\beta - \gamma - 3 - \frac{10}{3}\zeta - \kappa_1 + \frac{2}{3}\alpha_2 - \frac{2}{3}J_1 - \frac{1}{3}J_2 \right) \frac{\Omega_a}{m_a}$$

$$\begin{aligned} \frac{(m_A)_b}{m_b} &= 1 - \left(4\beta - \gamma - 3 - \frac{10}{3}\zeta - \frac{1}{2}\alpha_3 - \frac{1}{3}J_1 - 2J_2 \right) \frac{\Omega_b}{m_b} \\ &\quad + J_3 \frac{E_b}{m_b} - \left(\frac{3}{2}\alpha_3 + J_1 - 3J_4 \right) \frac{P_b}{m_b} \end{aligned}$$

$$\Omega_a = -\frac{1}{2} \int_a \frac{\rho \rho'}{|x-x'|} d^3x d^3x'$$

$$E_a = \int_a \rho \Pi d^3x$$

$$P_a = \int_a \rho v^i dx^i$$

Note $m_p \neq m_{\text{I}}$ - violation of WEP for massive bodies
 - Nordtvedt effect

Note $m_p \neq m_A$ - violation of 3rd law. Dist if

$$\alpha_3 = \beta_1 = \beta_2 = \beta_3 = \beta_4 = 0, \quad m_p = m_A$$

"n-body"

PPT

5. Equations of Motion - Spinning bodies

Gyroscope \vec{S} - spatial in comoving LFF frame
 - constant (if torque free)

$$S_0 = 0 \quad \vec{S} \cdot \vec{u} = 0 \quad S_0 \dot{u}^0 + S_j \dot{u}^j = 0 \quad \boxed{S_0 = -S_j v^j}$$

$$\frac{dS_j}{dt} = u^\alpha S_{j,\alpha} = 0 \Rightarrow u^\alpha S_{\mu;j\alpha} = \nabla_{\vec{u}} \vec{S} = 0$$

$$u^\alpha (S_{\mu;\alpha} - \Gamma_{\mu\alpha}^\beta S_\beta) = 0$$

$$\frac{dS_j}{dt} = \left(\Gamma_{j0}^0 S_0 + \Gamma_{jk}^0 S_0 v^k + \Gamma_{j0}^l S_l + \Gamma_{jk}^l S_l v^k \right)$$

$$\Gamma_{j0}^0 = -U_{,j} \quad \Gamma_{jk}^0 = \gamma \delta_{jk} \dot{U}$$

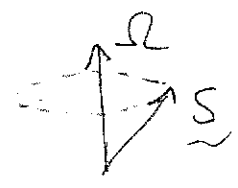
$$\Gamma_{j0}^l = \delta \delta_{lj} \dot{U} - \frac{1}{2} (\gamma + \gamma + \alpha_1) V_{[l,j]}$$

$$\Gamma_{jk}^l = \delta (\delta_{jl} U_{,k} + \delta_{jk} U_{,l} - \delta_{jk} U_{,l})$$

$$\frac{d\vec{S}}{dt} = \vec{\Omega} \times \vec{S}$$

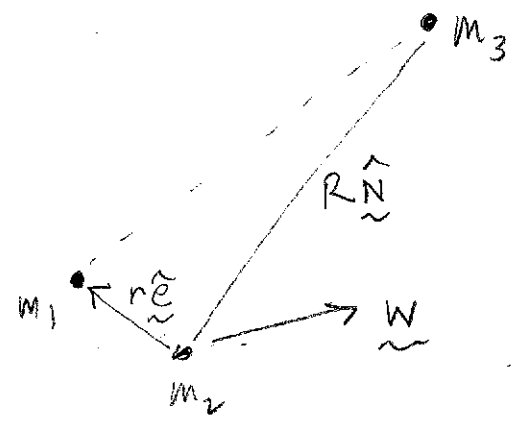
$$\vec{\Omega} = -\frac{1}{4}(4\gamma + 4 + \alpha_1) \nabla \times \vec{V} + (\gamma + \frac{1}{2}) \vec{v} \times \nabla U$$

precession



6. Locally Measured G

$$m_1 \frac{d^2 r_p}{dt^2} = -\frac{m_1 m_2}{r_p^2} \hat{e}_L$$



at rest \Rightarrow all comes from g_{00}

$$U = \frac{m_2}{r_{12}} + \frac{m_3}{|r_{e2} - R\hat{N}|}$$

$$\Phi_{12} = \frac{m_2}{r_{12}} \left(\frac{m_3}{R} \right) + O\left(\frac{1}{R^2}\right)$$

$$\Phi_w = \frac{m_2}{r_{12}} \frac{m_3}{R} (2 - (\hat{e} \cdot \hat{N})^2) + O\left(\frac{1}{R^2}\right)$$

$$U'' = \frac{m}{r} \left[1 - (4\beta - 3\gamma - 1 - \beta_2 - 3\beta) \frac{m_3}{R} + \beta \frac{m_3}{R} (\hat{e} \cdot \hat{N})^2 - \frac{1}{2}(\alpha_1 - \alpha_2 - \alpha_3) w^2 - \frac{1}{2} \alpha_4 (w \cdot \hat{e})^2 \right]$$

convert to proper η, t ,