# **Evolution Problem in Numerical Relativity**

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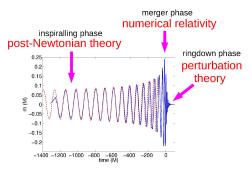
# Context

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## Context: Numerical Relativity

- Numerical Relativity: Solve Einstein's equations (or more) numerically.
- Black Hole Binary Grand Challenge (90s): achieve several orbits and merger to generate waveforms for Gravitational Waves emission.



Picture from http://www.iap.fr/actualites/laune/2016/OndesGr/forme\_onde\_an.jpg

Image: A matrix and a matrix



- Numerical Relativity: Solve Einstein's equations (or more) numerically.
- Black Hole Binary Grand Challenge (90s): achieve several orbits and merger to generate waveforms for Gravitational Waves emission.
- In 2005, first successful simulation by Pretorius (https://doi.org/10.1103/PhysRevLett.95.121101)
- In 2015, first successful detection of GW (https://doi.org/10.1103/PhysRevLett.116.061102)



- To obtain a successful computation, you need a handful of ingredients, mixed together in a delicate and sometimes empirical manner.
- Put it in the oven of High Performance Computing for thousands of CPU hours.
- See for example Brügmann in *Science* for a short review https://science.sciencemag.org/content/361/6400/366

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#### An overview of a few ingredients

- System of equations:
  - Choice of theory
  - Choice of dynamical variables
  - Choice of the order of equations (in time, in space)
  - Constraint damping...
- Discretization, integration scheme, numerical methods, parallelization.
- Gauge conditions, boundary conditions, initial data.
- Management of the physical objects (horizons, shocks) and extraction of relevant data (gravitational waveform).



- First: Start with standard methods and implement them in Kadath, to have a working code.
- Second: Apply them to new physical systems (AADS spacetimes, scalar-tensor theories...) and/or explore less standard methods (constrained evolution schemes, time spectral methods).

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# Brief introduction to Kadath and my contribution



- Kadath library: numerical code (C++) developed at LUTH which implements spectral methods and a Newton-Raphson scheme to solve non-linear PDEs.
- Can be used to study stationary systems or generate initial data for evolution for example.
- Very flexible in terms of geometry, equations to solve, designed with NR in mind, but no evolving systems yet (hence PhD).

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What's new?			

- Solve hyperbolic systems of equations with
  - a 4th-order Runge-Kutta scheme ;
  - an adaptive step Runge-Kutta scheme (Dormand-Prince method).
- Equations given as  $\partial_t u = \dots$  with u being one of the dynamical variables, for bulk, boundary and matching equations.
- Implemented for spherical types of spaces (nucleus and shell domains) but easily transferable to other types of domains and spaces when needed.
- Save configurations with a custom frequency (e.g. every 10 time steps) or stop the time scheme with numerical or physical criteria.

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A first application: the scalar wave



- Simple and controlled toy-model to proof test the code.
- The Einstein equations in Generalized Harmonic Gauge have a wave-like structure.
- Allows to test and familiarize with various aspects independently:
  - 1D/3D
  - various kinds of boundary conditions
  - constraint damping
  - penalty methods
  - self-interaction.
- Illustration of a few items here.



• 
$$\frac{\partial^2 N}{\partial t^2} = c^2 \frac{\partial^2 N}{\partial r^2}$$

• First-order reduction: Use the space and time derivatives (resp. G and V) as independent variables

$$\begin{cases} \partial_t N = cV \\ \partial_t G = c\partial_r V \\ \partial_t V = c\partial_r G \end{cases}$$

• Free evolution: the constraint  $C = G - \partial_r N$  is not evolved. (Rem: C(t = 0) = 0 and  $\partial_t C = \partial_t G - \partial_t (\partial_r N) = c \partial_r V - c \partial_r V = 0$ )  $\Rightarrow$  It can be used as a measure of the numerical convergence.

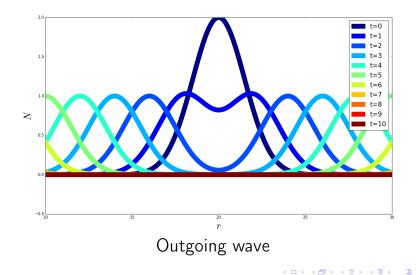
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# Illustration



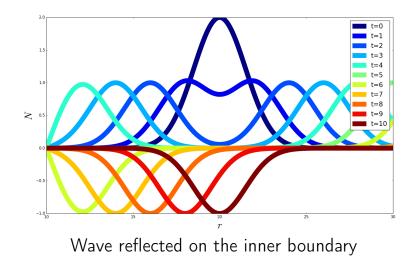
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# Illustration



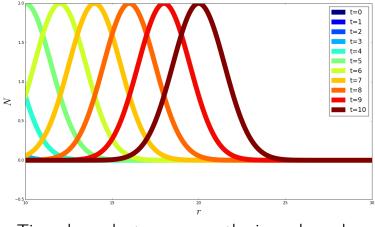
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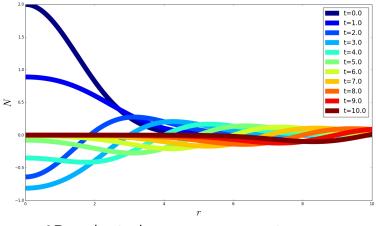
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# Illustration



Time-dependent source on the inner boundary

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Illustration			



# 3D, spherical symmetry, outgoing wave

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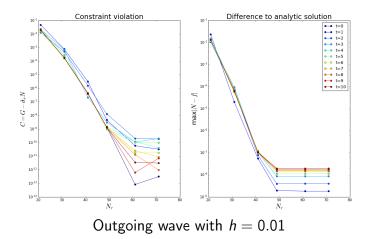
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## Some convergence results (1D)

#### Spectral convergence

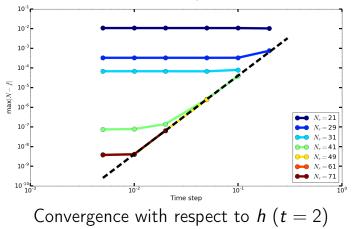


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#### Time-step convergence

Difference to analytic solution



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Idea: No need to impose exact boundary conditions on the approximate (aka discretized) system.
 ⇒ The boundary conditions are included in the bulk equations as a

penalty term.

$$\operatorname{EOM}(u) + \kappa Q(x) \cdot \operatorname{BC}(u) = 0$$

• Schematically, 
$$\kappa \xrightarrow[N \to \infty]{} +\infty$$
 and  $Q(x) = \delta(x - x_{
m BC})$ 

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- Yields more stable schemes for spectral methods, allows more variety on boundary types and conditions (see for example Hesthaven https://doi.org/10.1016/S0168-9274(99)00068-9).
- Reduces the number of equations to compute in Kadath.
- Following Taylor *et al.*, way to go for second-order-in-space systems (https://doi.org/10.1103/PhysRevD.82.024037).
   ⇒ Reduces the number of variables, equations and constraints.
- Works in Kadath for the scalar wave, for boundary and matching conditions, 1D/3D, 1st and 2nd order in space.

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# Current and future work

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<b>Context</b>	Kadath	Scalar wave	Conclusion
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Conclusion			

- Achieved work:
  - Implement a solver for evolution equations in Kadath
  - Validate it with the scalar wave
  - Use this toy-model to get familiar with various ingredients required for the evolution problem in GR.
- Current work: Compute the evolution of a GR system. Initial data consisting in gravitational waves (Teukolsky wave).
- Future work: Apply the code to new systems (e.g. stability of geons in AAdS spacetime, stability of black holes in modified gravity).

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