

Averaging in spatially homogenous
Einstein-Klein-Gordon cosmology



Gernot Heißel

Meudon, 27.02.2020

Introducing myself

- ❖ 2 year Postdoc @ LESIA in GRAVITY group
- ❖ Main project: probe possibility of detection of extended mass distribution between S2 and SBH @ galactic centre.
→ celestial mechanics. newtonian, post newtonian, relativistic
- ❖ Studied Physics in Innsbruck (BSc), Vienna (MSc) and Cardiff (PhD)
- ❖ PhD thesis with Mark Hannam on black hole initial data for 3+1 simulations (under umbrella of LSC)
- ❖ MSc thesis with Mark Heinzle and first Postdoc in Vienna with David Fajman on mathematical cosmology. → spatially homogenous cosmology with various matter models.

Spatially homogenous cosmology

Friedman
cosmology

analytically

inhomogenous
cosmology

(generally)
numerically

Spatially homogenous cosmology

Friedman
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analytically

spatially
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numerically



eg exact past &
future asymptotic
dynamics

- ❖ D Fajman, G Heiel, M Maliborski
On the oscillations and future asymptotics of locally rotationally symmetric Bianchi type III cosmologies with a massive scalar field
arXiv:2001.00252, submitted for publication

- ❖ D Fajman, G Heiel, JW Jang
Averaging with a time dependent perturbation
drafting

- ❖ D Fajman, G Heiel
Averaging methods in spatially homogenous Einstein-Klein-Gordon cosmology
drafting

SH scalar field cosmology

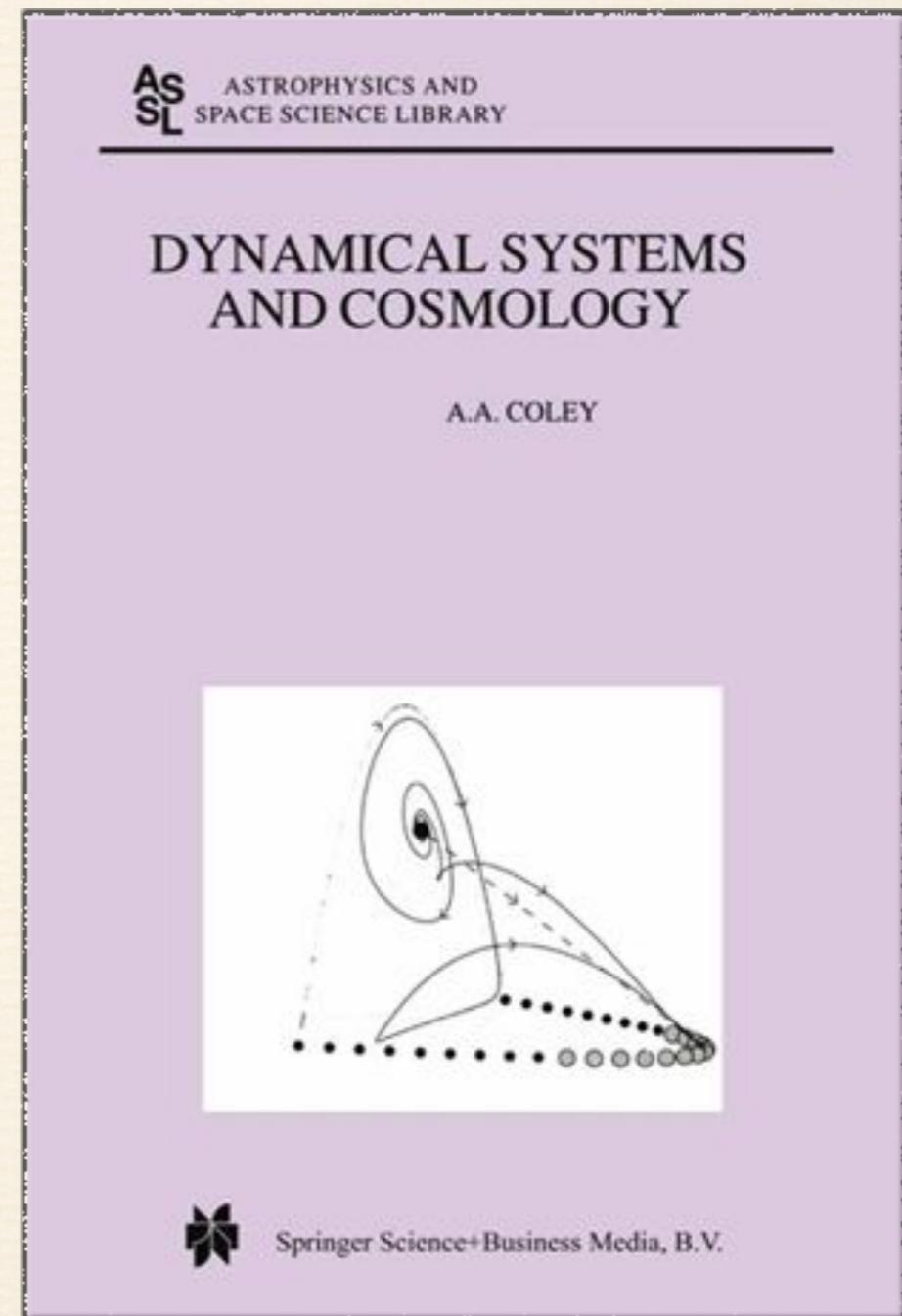
$$\diamond R_{ab} - \frac{R}{2}g_{ab} = T_{ab}$$

$$T_{ab} = \nabla_a \phi \nabla_b \phi - \left(\frac{1}{2} \nabla_c \nabla^c \phi + V(\phi) \right) g_{ab}$$

$$\square_g \phi = V'(\phi)$$

- Formulate Einstein-matter eqs as dynamical system in expansion (/Hubble) normalised variables.

$$H := \left(\frac{\dot{a}}{a} + 2 \frac{\dot{b}}{b} \right) / 3$$

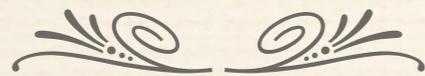


(2003)

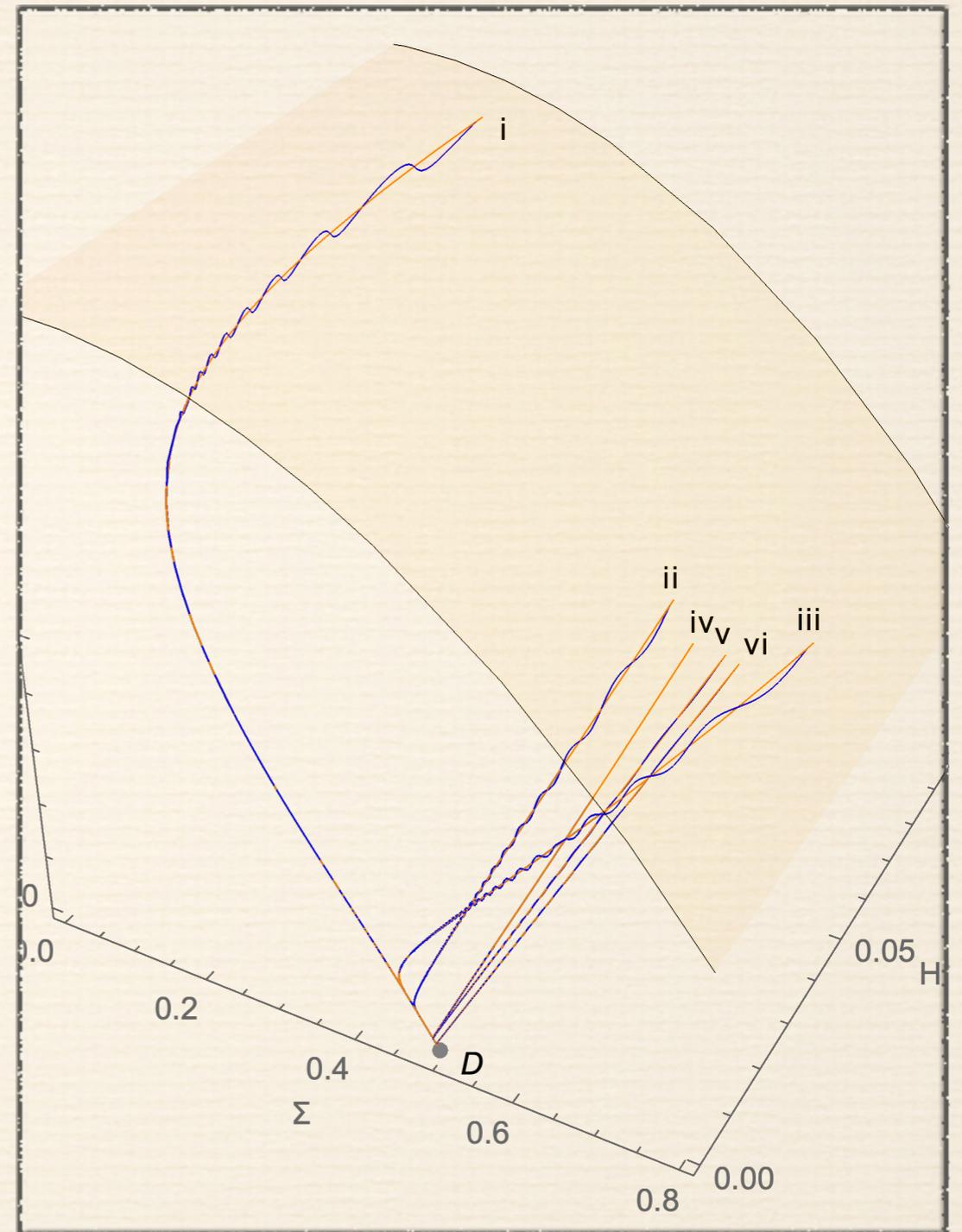
- ❖ Exponential potential: $V(\phi) \propto e^{\kappa\phi}$
 - Interesting in the context of inflation.
 - $V'(\phi) \propto V(\phi) \Rightarrow$ Raychaudhuri eq $\dot{H}(t) = \dots$ decouples
 - Asymptotics related to equilibrium points of the reduced system.
 - Dynamical systems analysis to determine asymptotics.

- ❖ Harmonic potential: $V(\phi) = m^2\phi^2/2$
 - Massive scalar field / Klein-Gordon field.
 - Raychaudhuri eq does *not* decouple.
 - Standard dynamical systems approach *not* a priori applicable.

LRS Bianchi III Einstein-Klein- Gordon



D Fajman, G Heißel, M Maliborski
arXiv:2001.00252
submitted for publication



- ❖ Choose formulation of Rendall & Uggla (2000)

$$\mathbf{g} = - dt^2 + a(t)^2 dr^2 + b(t)^2 \mathbf{g}_{H^2}$$

$$H := \frac{1}{3} \left(\frac{\dot{a}}{a} + 2 \frac{\dot{b}}{b} \right) \quad \text{Hubble scalar}$$

$$\Sigma_+ := \frac{1}{3H} \left(\frac{\dot{a}}{a} - \frac{\dot{b}}{b} \right) \quad \text{shear variable}$$

$$T^a_b = \text{diag}(-\rho, p_1, p_2, p_3)$$

- ❖ Plug in $m = 1$ Klein-Gordon field into their equations

$$\rho = \frac{1}{2} (\dot{\phi}^2 + \phi^2)$$

$$p_i = \frac{1}{2} (\dot{\phi}^2 - \phi^2)$$

❖ Define

$$q := 2\Sigma_+^2 + \frac{1}{6H^2} (2\dot{\phi}^2 - \phi^2) \quad \text{deceleration parameter}$$

$$\Omega := \frac{\rho}{3H^2} \quad \text{rescaled energy density}$$

❖ Yields reduced system

$$\left. \begin{aligned} \dot{H} &= H^2 [- (1 + q)] \\ \dot{\Sigma}_+ &= H [- (2 - q)\Sigma_+ + 1 - \Sigma_+^2 - \Omega] \end{aligned} \right\} \text{Einstein evol.}$$

$$\boxed{\ddot{\phi} + \phi = H [- 3\dot{\phi}]} \quad \text{Klein-Gordon}$$

$$1 > \Sigma_+^2 + \Omega \quad \text{Hamiltonian constraint}$$

The Van der Pol equation

- ❖ Consider general class of Van der Pol equations

$$\ddot{\phi} + \phi = \epsilon g(\dot{\phi}, \phi), \epsilon = \text{const} \quad \text{vs} \quad \ddot{\phi} + \phi = H[-3\dot{\phi}], H = H(t)$$

- ❖ Apply amplitude phase (variation of constants) transformation

$$\begin{aligned} \phi &= r \sin(t - \varphi) \\ \dot{\phi} &= r \cos(t - \varphi) \end{aligned} \quad \Rightarrow \quad \begin{bmatrix} \dot{r} \\ \dot{\varphi} \end{bmatrix} = \epsilon \begin{bmatrix} \cos(t - \varphi) g(\phi, \dot{\phi}) \\ \frac{1}{r} \sin(t - \varphi) g(\phi, \dot{\phi}) \end{bmatrix} =: \epsilon \mathbf{f}^1(t, r, \varphi)$$

- ❖ Note that $\mathbf{f}^1(t, r, \varphi)$ is 2π periodic in t .

- ❖ Idea: take time average of right hand side function

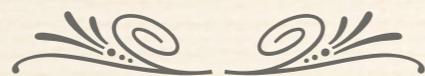
$$\bar{\mathbf{f}}^1(r, \varphi) := \frac{1}{2\pi} \int_0^{2\pi} \mathbf{f}^1(s, r, \varphi) ds$$

- ❖ Construct averaged system

$$\begin{bmatrix} \dot{\bar{r}} \\ \dot{\bar{\varphi}} \end{bmatrix} = \epsilon \bar{\mathbf{f}}^1(\bar{r}, \bar{\varphi})$$

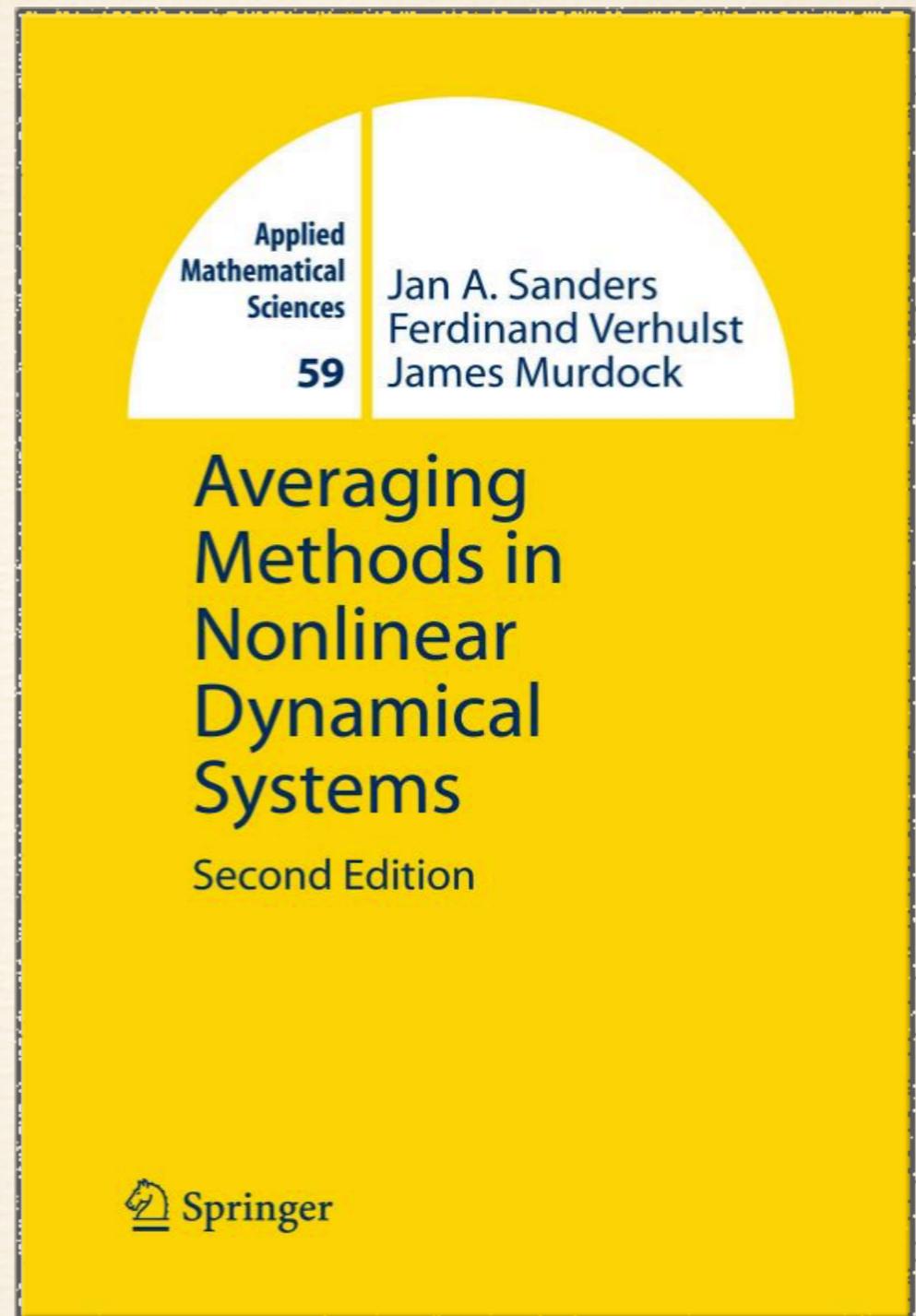
- ❖ How good is this approximation?

Theory of averaging



*... originally motivated by
celestial mechanics*

→ perturbed 2 body problem, etc.



(2007)

❖ **Theorem 1** (periodic averaging)

$$\dot{\mathbf{x}} = \epsilon \mathbf{f}^1(\mathbf{x}, t) + \epsilon^2 \mathbf{f}^{[2]}(\mathbf{x}, t, \epsilon), \quad \mathbf{x}(0) = \mathbf{a}$$

- $\mathbf{f}^1, \mathbf{f}^{[2]}$ T -periodic in t
- \mathbf{f}^1 Lipschitz, $\mathbf{f}^{[2]}$ continuous

$$\dot{\mathbf{z}} = \epsilon \bar{\mathbf{f}}^1(\mathbf{z}), \quad \mathbf{z}(0) = \mathbf{a}, \quad \bar{\mathbf{f}}^1(\mathbf{z}) = \frac{1}{T} \int_0^T \mathbf{f}^1(\mathbf{z}, s) ds$$

Then $\mathbf{x}(t) - \mathbf{z}(t) = \mathcal{O}(\epsilon)$ on timescales of order ϵ^{-1} .

❖ **Theorem 2** (Eckhaus/Sanchez-Palencia)

$$\dot{\mathbf{x}} = \epsilon \mathbf{f}^1(\mathbf{x}, t), \quad \mathbf{x}(0) = \mathbf{a} \quad \dot{\mathbf{z}} = \epsilon \bar{\mathbf{f}}^1(\mathbf{z}), \quad \mathbf{z}(0) = \mathbf{a}, \quad \mathbf{f}^1 \text{ KBM}$$

If $\mathbf{z} = 0$ is an asymptotically stable equilibrium point of the linearisation...

...then $\mathbf{x}(t) - \mathbf{z}(t) = \mathcal{O}(\epsilon)$ for $0 \leq t < \infty$.

Back to LRS Bianchi III

❖ Equations in $\{H, \Sigma_+, \phi, \dot{\phi}\}$

$$\dot{H} = H^2 [- (1 + q)]$$

$$\dot{\Sigma}_+ = H [- (2 - q)\Sigma_+ + 1 - \Sigma_+^2 - \Omega]$$

$$\ddot{\phi} + \phi = H [- 3\dot{\phi}]$$

$$\Sigma_+^2 + \Omega < 1 \quad \text{Hamiltonian constraint}$$

❖ Amplitude phase (variation of constants) transformation

$$\begin{aligned} \phi &= r \sin(t - \varphi) \\ \dot{\phi} &= r \cos(t - \varphi), \end{aligned} \quad r \mapsto \Omega = \frac{r^2}{6H^2} \quad \Longrightarrow \quad q = 2\Sigma_+^2 + \Omega(3 \cos(t - \varphi)^2 - 1)$$

❖ Equations in $\{H, \Sigma_+, \Omega, \varphi\}$

$$\dot{H} = H^2 [-(1+q)]$$

$$\dot{\Sigma}_+ = H [-(2-q)\Sigma_+ + 1 - \Sigma_+^2 - \Omega]$$

$$\dot{\Omega} = H [2\Omega(1+q - 3\cos(t-\varphi)^2)]$$

$$\dot{\varphi} = H [-3\sin(t-\varphi)\cos(t-\varphi)]$$

$$1 > \Sigma_+^2 + \Omega$$

❖ Writing $\mathbf{x} = [\Sigma_+, \Omega, \varphi]^T$ this has the form

$$\begin{bmatrix} \dot{H} \\ \dot{\mathbf{x}} \end{bmatrix} = H \mathbf{F}^1(\mathbf{x}, t) + H^2 \mathbf{F}^{[2]}(\mathbf{x}, t) = H \begin{bmatrix} 0 \\ \mathbf{f}^1(\mathbf{x}, t) \end{bmatrix} + H^2 \begin{bmatrix} f^{[2]}(\mathbf{x}, t) \\ \mathbf{0} \end{bmatrix}$$

analogous to a periodic perturbation problem in standard form

$$\dot{\mathbf{x}} = \epsilon \mathbf{f}^1(\mathbf{x}, t) + \epsilon^2 \mathbf{f}^{[2]}(\mathbf{x}, t, \epsilon).$$

❖ Difference: $\rightarrow H(t)$ is time dependent ...

\rightarrow ... and itself subject to evolution equation which is part of the system

❖ Idea: View this as an averaging problem with time dependent perturbation function.

❖ Equations in $\{H, \Sigma_+, \Omega, \varphi\}$

$$\dot{H} = H^2[-(1+q)]$$

$$\dot{\Sigma}_+ = H[-(2-q)\Sigma_+ + 1 - \Sigma_+^2 - \Omega]$$

$$\dot{\Omega} = H[2\Omega(1+q - 3\cos(t-\varphi)^2)]$$

$$\dot{\varphi} = H[-3\sin(t-\varphi)\cos(t-\varphi)]$$

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❖ Difference: $\rightarrow H(t)$ is time dependent ...

$\rightarrow \dots$ and itself subject to evolution equation which is part of the system

❖ Idea: View this as an averaging problem with time dependent perturbation function.

Same core idea independently before us:

A Alho & C Uggla (2015)

A Alho et al (2015)

A Alho et al (arXiv, 2019)

❖ Full eq

$$\dot{\mathbf{x}} = \epsilon \mathbf{f}^1(\mathbf{x}, t) + \epsilon^2 \mathbf{f}^{[2]}(\mathbf{x}, t, \epsilon)$$

❖ Averaged eq

$$\dot{\mathbf{z}} = \epsilon \bar{\mathbf{f}}^1(\mathbf{z})$$

❖ Theorem

On timescales of order ϵ^{-1}

$$\mathbf{x}(t) - \mathbf{z}(t) = \mathcal{O}(\epsilon)$$

❖ Full eq

$$\begin{bmatrix} \dot{H} \\ \dot{\mathbf{x}} \end{bmatrix} = H \begin{bmatrix} 0 \\ \mathbf{f}^1(\mathbf{x}, t) \end{bmatrix} + H^2 \begin{bmatrix} f^{[2]}(\mathbf{x}, t) \\ \mathbf{0} \end{bmatrix}$$

❖ Averaged eq

$$\dot{\mathbf{z}} = H(t) \bar{\mathbf{f}}^1(\mathbf{z})$$

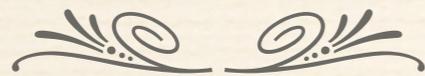
❖ Conjecture

$\exists t_*$ such that $\forall t > t_*$

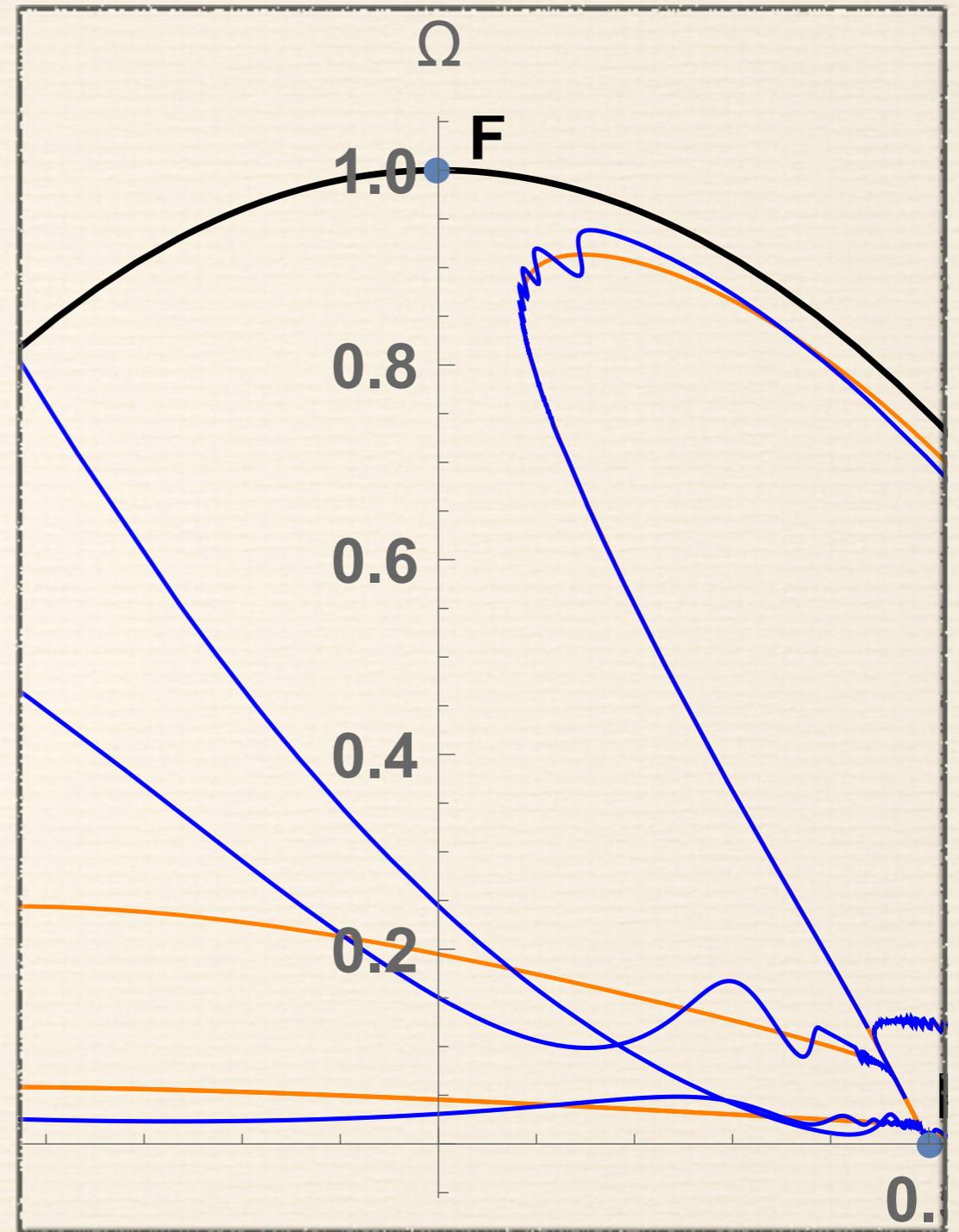
$$\mathbf{X}(t) - \mathbf{Z}(t) = \mathcal{O}(H(t))$$

❖ Lemma. H is strictly decreasing with t and $\lim_{t \rightarrow \infty} H(t) = 0$.

Analytical support for the conjecture



Back to LRS Bianchi III



❖ Start with full system

$$\begin{bmatrix} \dot{H} \\ \dot{\mathbf{x}} \end{bmatrix} = H \begin{bmatrix} 0 \\ \mathbf{f}^1(\mathbf{x}, t) \end{bmatrix} + H^2 \begin{bmatrix} f^{[2]}(\mathbf{x}, t) \\ \mathbf{0} \end{bmatrix}$$

❖ Truncate to first order after sufficiently large $t = t_*$ $\Rightarrow H^2 \ll H \ll 1$

$$\begin{bmatrix} \dot{\mathcal{H}} \\ \dot{\mathbf{y}} \end{bmatrix} = \begin{bmatrix} 0 \\ \mathcal{H} \mathbf{f}^1(\mathbf{y}, t) \end{bmatrix} = \begin{bmatrix} 0 \\ H_* \mathbf{f}^1(\mathbf{y}, t) \end{bmatrix}, \text{ with } H_* = \mathcal{H}(t_*) = H(t_*)$$

❖ Assumption: $\mathbf{x}(t) - \mathbf{y}(t) = \mathcal{O}(H_*)$

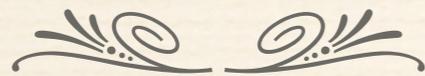
❖ Average first order system $\dot{\mathbf{z}} = H_* \bar{\mathbf{f}}^1(\mathbf{z})$

❖ By standard averaging Thm: $\mathbf{X}(t) - \mathbf{Y}(t) = \mathcal{O}(H_*)$

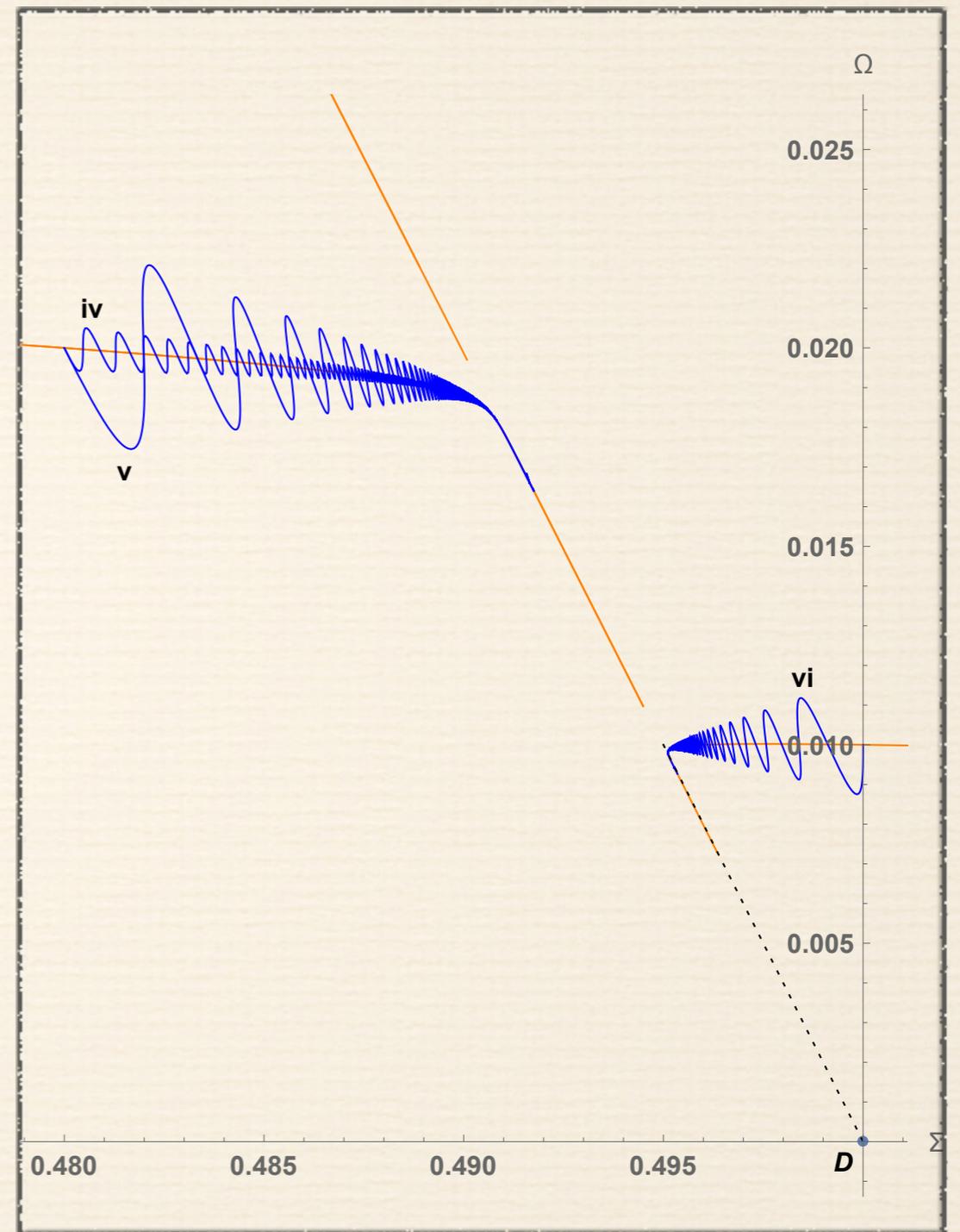
❖ Together with truncation error: $\mathbf{X}(t) - \mathbf{Z}(t) = \mathcal{O}(H_*)$

❖ Continuum limit yields statement of conjecture: $\mathbf{X}(t) - \mathbf{Z}(t) = \mathcal{O}(H(t))$

Future asymptotics of LRS Bianchi III E-K-G



*Under the premise that the conjecture
holds.*



❖ Transform to rescaled time

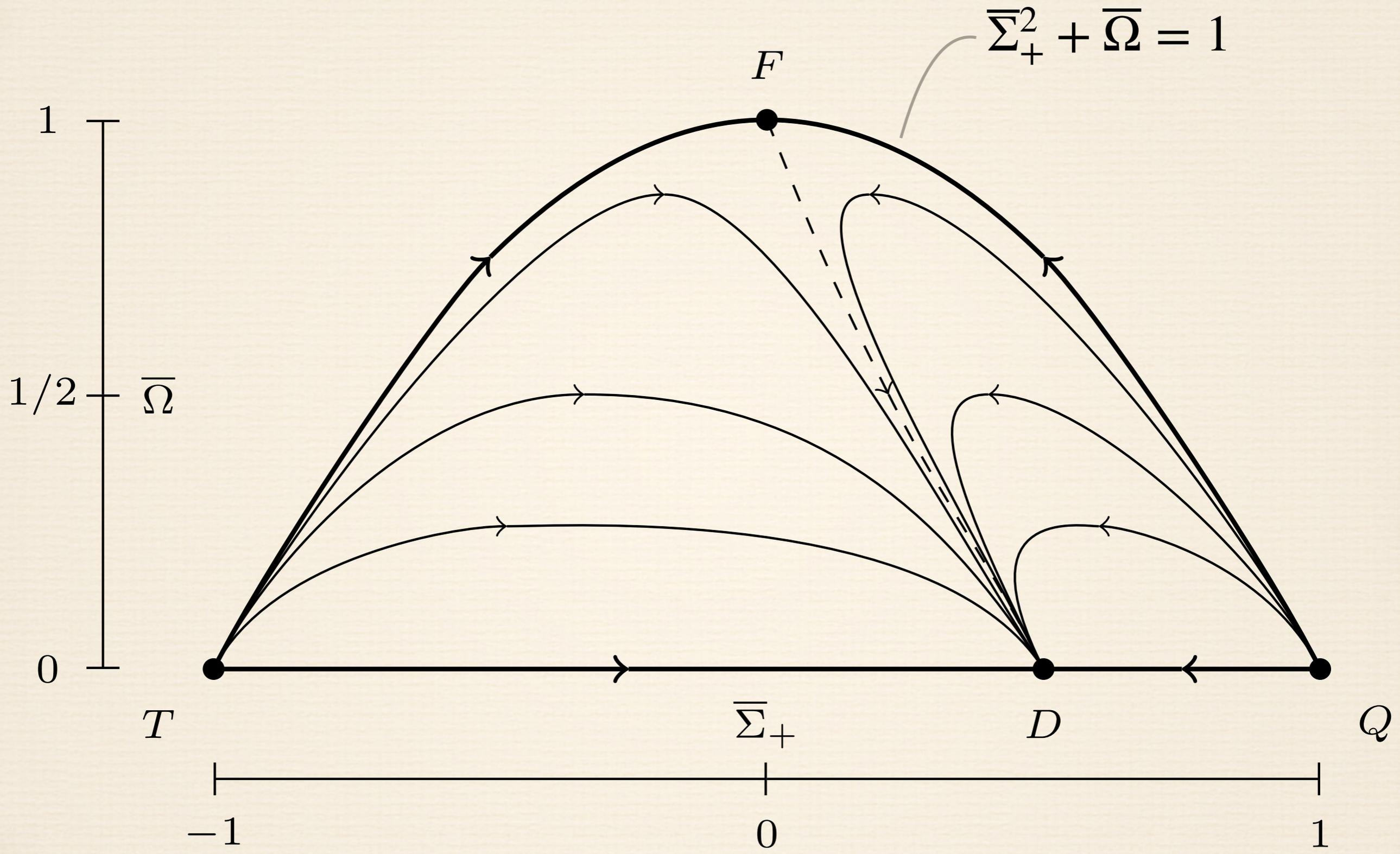
$$t \mapsto \tau := \int_{t_0}^t H(s) ds \quad \Longrightarrow \quad \partial_t = H \partial_\tau$$

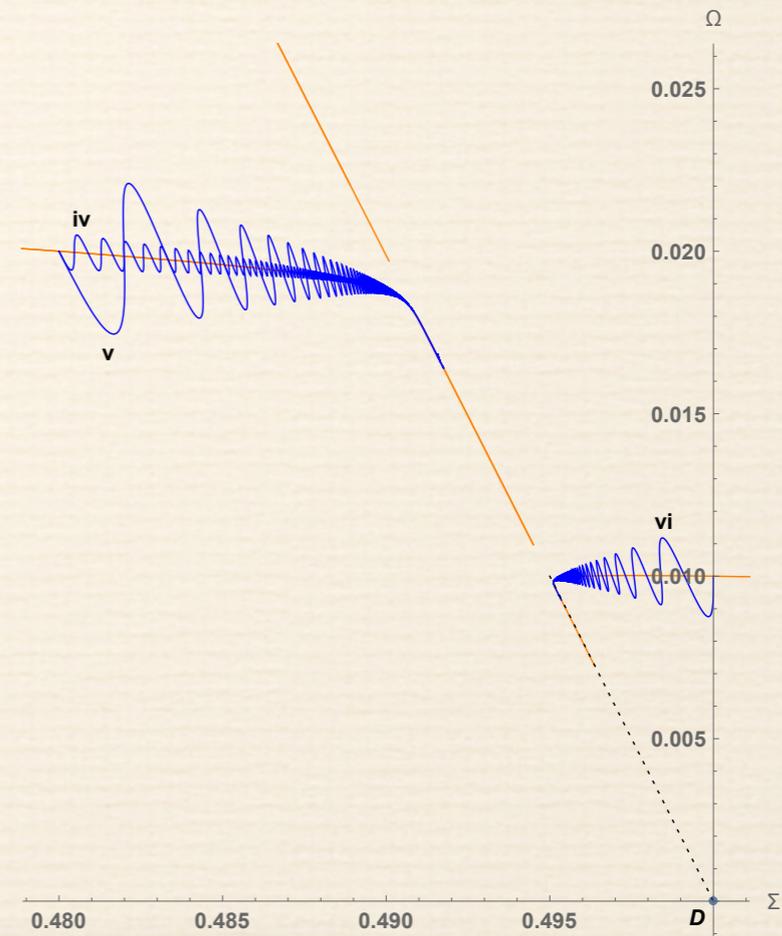
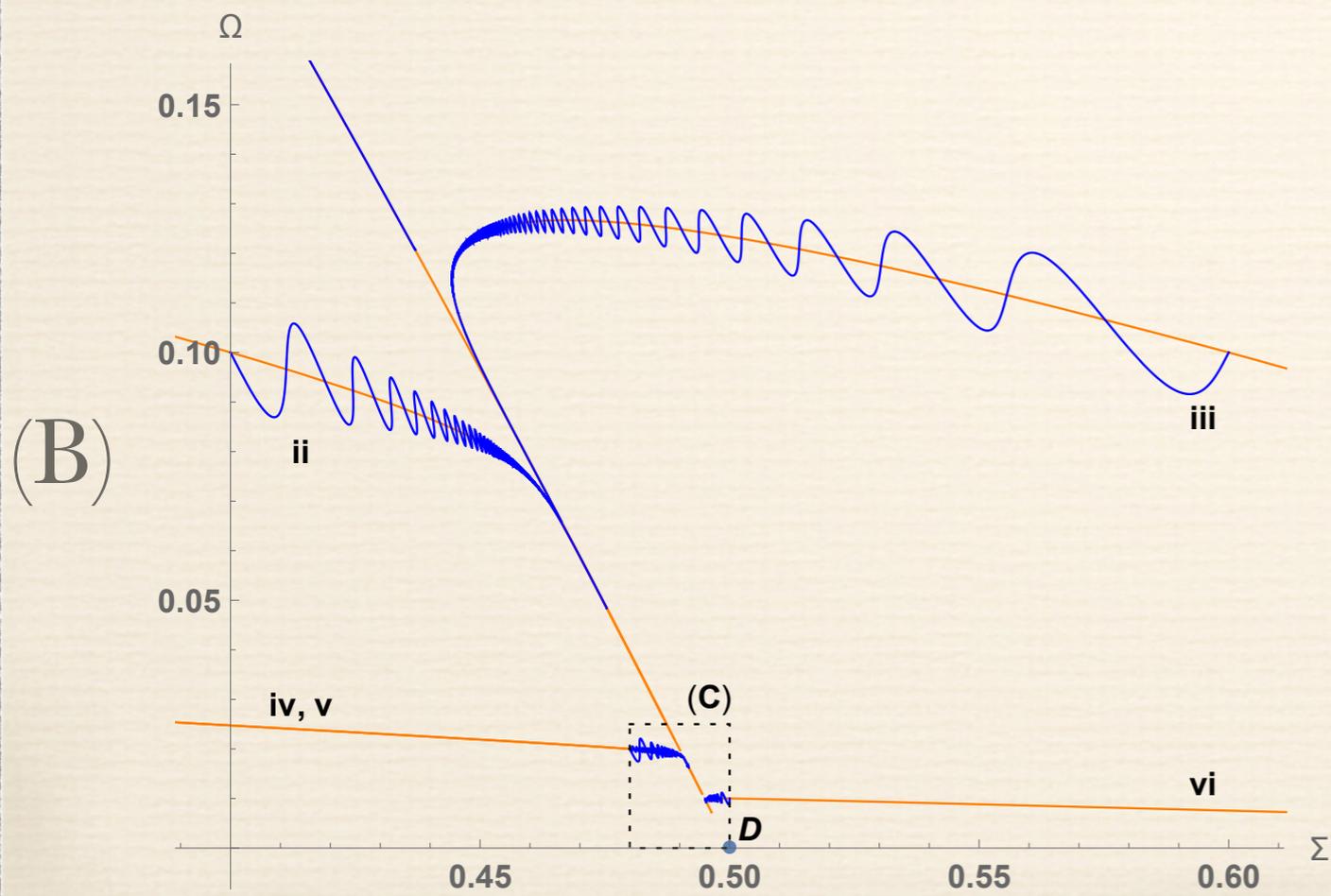
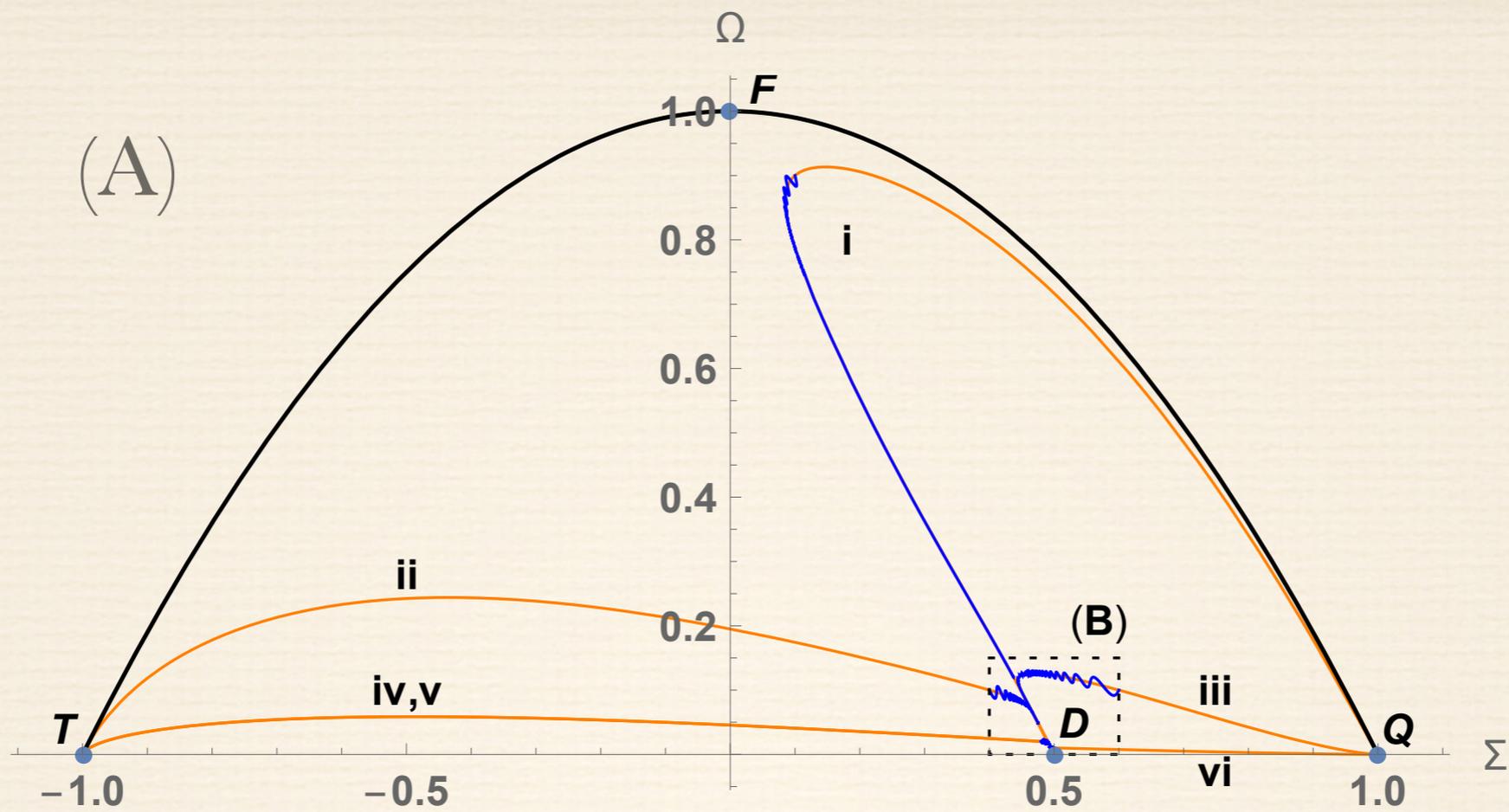
❖ System transforms to

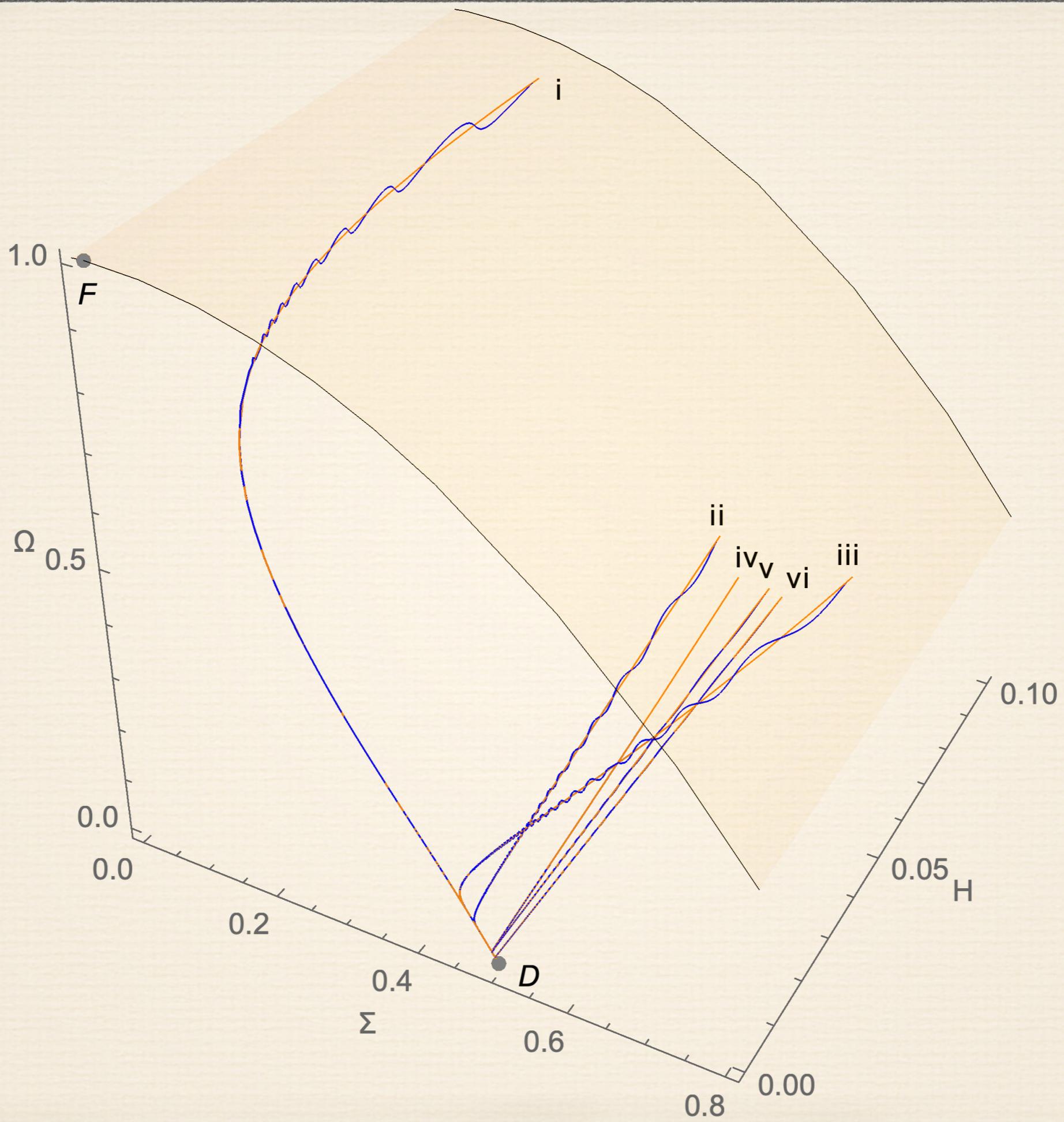
$$\begin{bmatrix} \dot{H} \\ \dot{\mathbf{x}} \end{bmatrix} = H \mathbf{F}^1(\mathbf{x}, \tau) + H^2 \mathbf{F}^{[2]}(\mathbf{x}, \tau) \quad \mapsto \quad \begin{bmatrix} \partial_\tau H \\ \partial_\tau \mathbf{x} \end{bmatrix} = \mathbf{F}^1(\mathbf{x}, \tau) + H \mathbf{F}^{[2]}(\mathbf{x}, \tau)$$

❖ Averaging to $\partial_\tau \bar{\mathbf{x}} = \bar{\mathbf{F}}^1(\mathbf{x}, \tau)$

$$\begin{bmatrix} \partial_\tau \bar{\Sigma}_+ \\ \partial_\tau \bar{\Omega} \\ \partial_\tau \bar{\varphi} \end{bmatrix} = \begin{bmatrix} -\left(2(1 - \bar{\Sigma}_+^2) - \frac{\bar{\Omega}}{2}\right) \bar{\Sigma}_+ + 1 - \bar{\Sigma}_+^2 - \bar{\Omega} \\ \bar{\Omega} \left(4\bar{\Sigma}_+^2 - (1 - \bar{\Omega})\right) \\ 0 \end{bmatrix}$$







Exact solutions associated with equilibrium points

- ❖ First, solve Raychaudhuri eq at equilibrium points

$$\dot{H} = H^2 [- (1 + q)], \quad q = 2\Sigma_+^2 + \Omega (3 \cos(t - \varphi)^2 - 1)$$

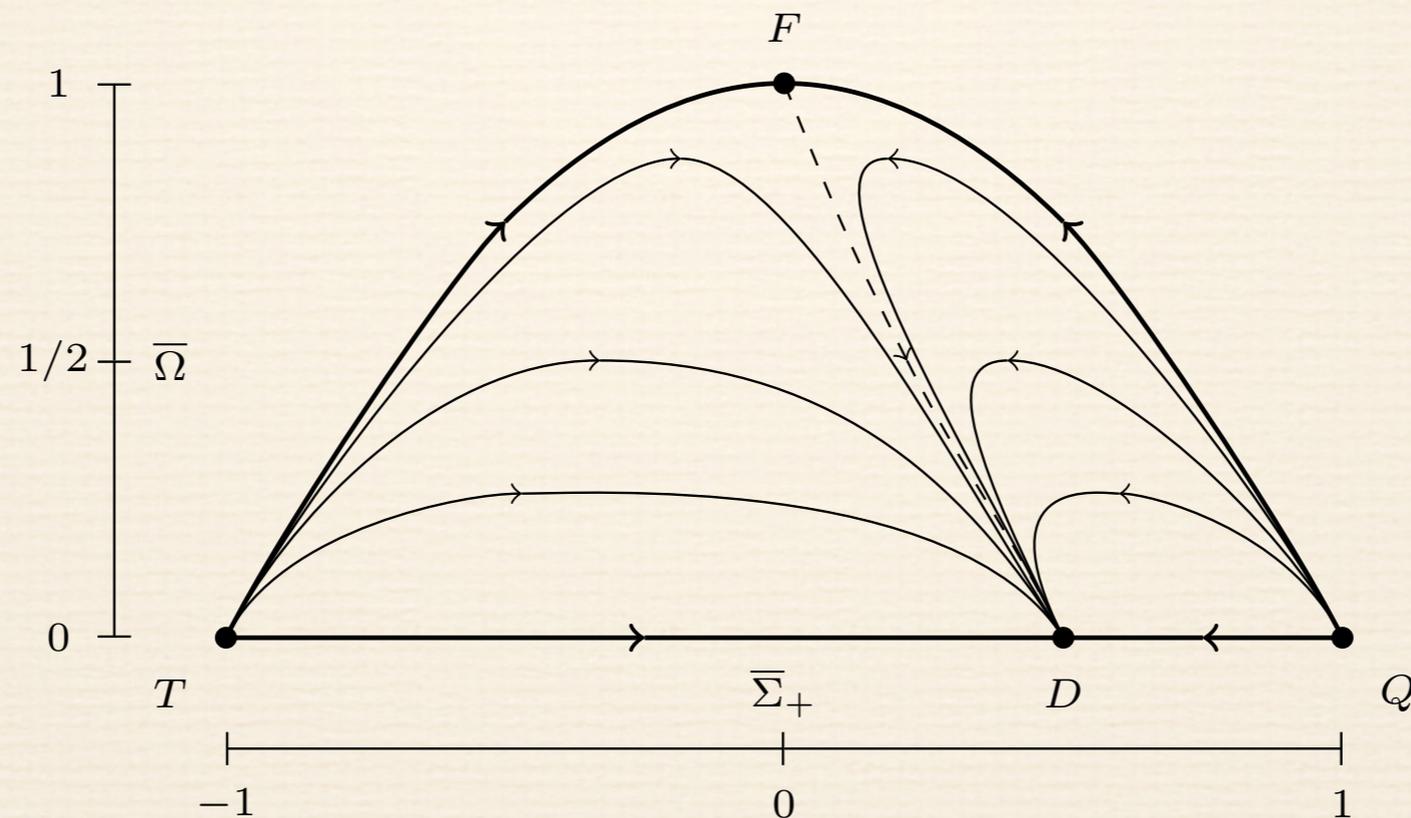
$$\xrightarrow{D} H(t) = \frac{2}{3t} \quad \text{for large } t$$

- ❖ Then, solve evolution eqs of the scale factors

$$\begin{array}{l} \dot{a} = aH(1 - 2\Sigma_+) \\ \dot{b} = bH(1 + \Sigma_+) \end{array} \quad \xrightarrow{D} \quad \begin{array}{l} a(t) = c_1 \\ b(t) = c_2 t \end{array}$$

$$\mathbf{g} = - dt^2 + a(t)^2 dr^2 + b(t)^2 \mathbf{g}_{H^2}$$

equil. point	$a(t)$	$b(t)$	solution
T	$c_1 t$	c_2	Taub (flat LRS Kasner)
Q	$c_1 t^{-1/3}$	$c_2 t^{2/3}$	non-flat LRS Kasner
D	c_1	$c_2 t$	Bianchi III form of flat spacetime
F	$c_1 t^{2/3}$	$c_2 t^{2/3}$	Einstein-de-Sitter (flat Friedman)



❖ Centre manifold analysis yields

Lemma.

$$\bar{\Sigma}_+ \approx \frac{1}{2} - \frac{1}{2\tau} \quad \text{and} \quad \bar{\Omega}(\tau) \approx \frac{1}{\tau} \quad \text{for large } \tau$$

❖ Assuming that conjecture $\mathbf{X}(t) - \mathbf{Z}(t) = \mathcal{O}(H(t))$ holds

Lemma. $H(t) \approx \frac{2}{3t}$ for large t

Lemma. $\tau(t) \approx \frac{2}{3} \ln t$ for large t $\left(t \mapsto \tau := \int_{t_0}^t H(s) ds \right)$

$$\implies \mathbf{X}(t) = \mathbf{Z}(t) + \mathcal{O}(H(t)) = \begin{bmatrix} \frac{1}{2} - \frac{3}{4 \ln t} \\ \frac{3}{2 \ln t} \end{bmatrix} + \mathcal{O}(t^{-1})$$

❖ ...

$$\implies \mathbf{X}(t) = \mathbf{Z}(t) + \mathcal{O}(H(t)) = \begin{bmatrix} \frac{1}{2} - \frac{3}{4 \ln t} \\ \frac{3}{2 \ln t} \end{bmatrix} + \mathcal{O}(t^{-1})$$

❖ **Theorem 1.** Assuming that the conjecture holds,

$$\Sigma_+(t) \approx \frac{1}{2} - \frac{3}{4 \ln t} \quad \text{and} \quad \Omega(t) \approx \frac{3}{2 \ln t} \quad \text{for large } t$$

❖ **Theorem 1.** Assuming that the conjecture holds,

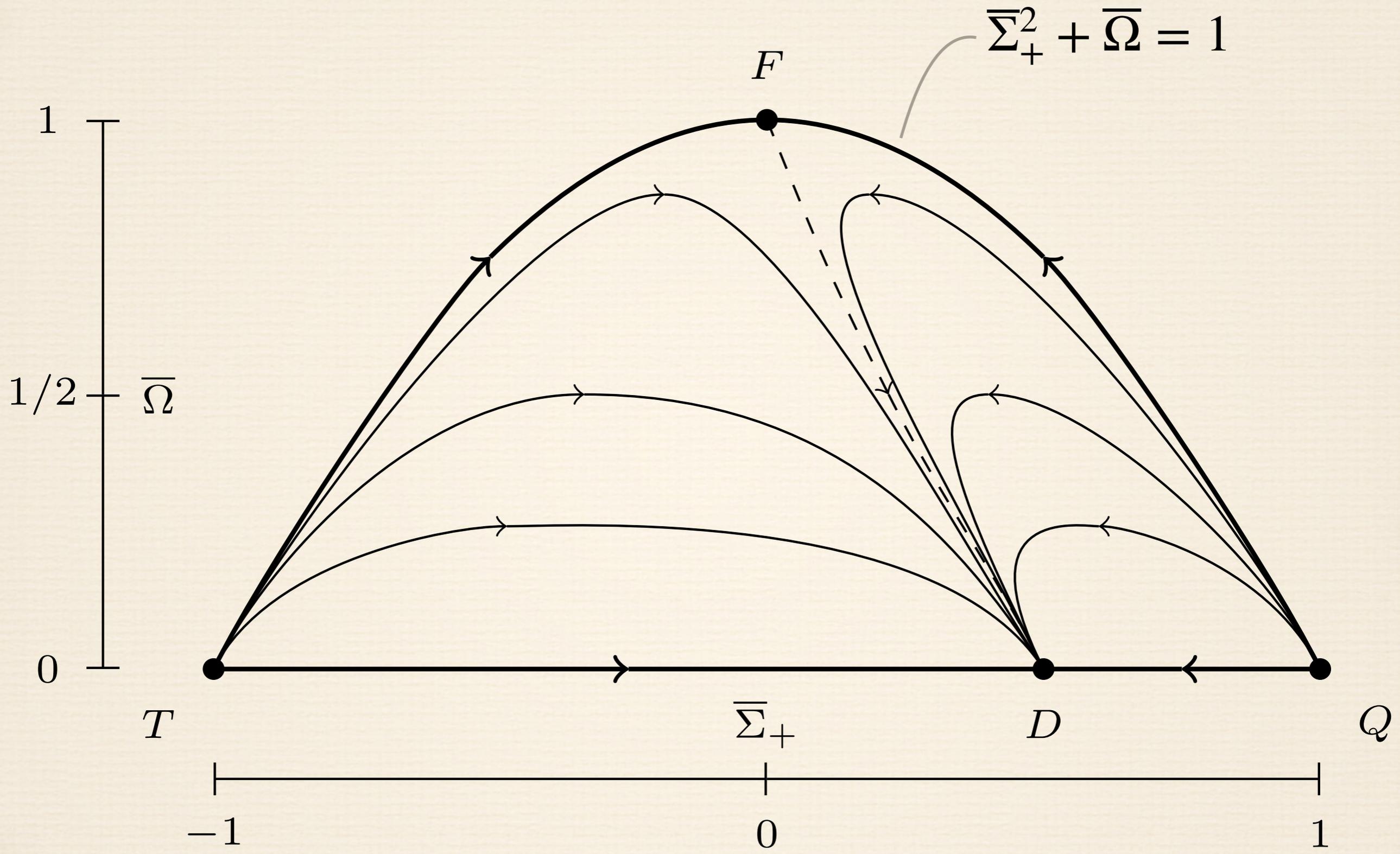
$$\Sigma_+(t) \approx \frac{1}{2} - \frac{3}{4 \ln t} \quad \text{and} \quad \Omega(t) \approx \frac{3}{2 \ln t} \quad \text{for large } t.$$

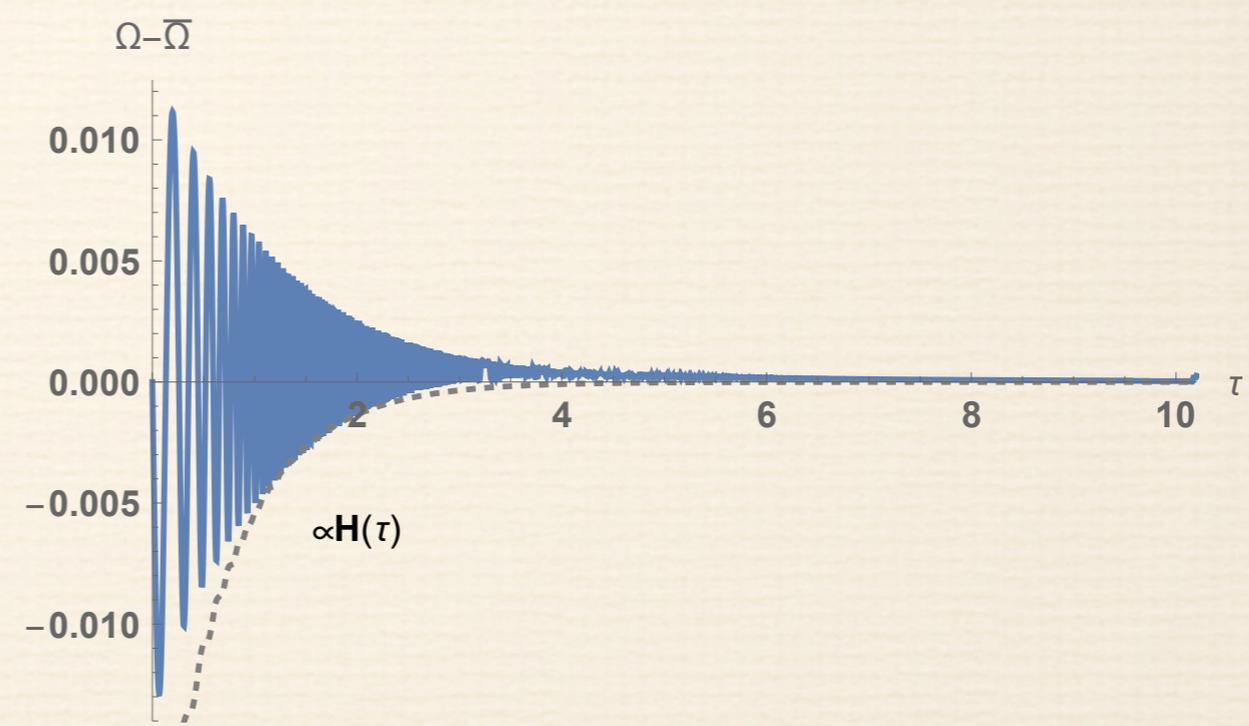
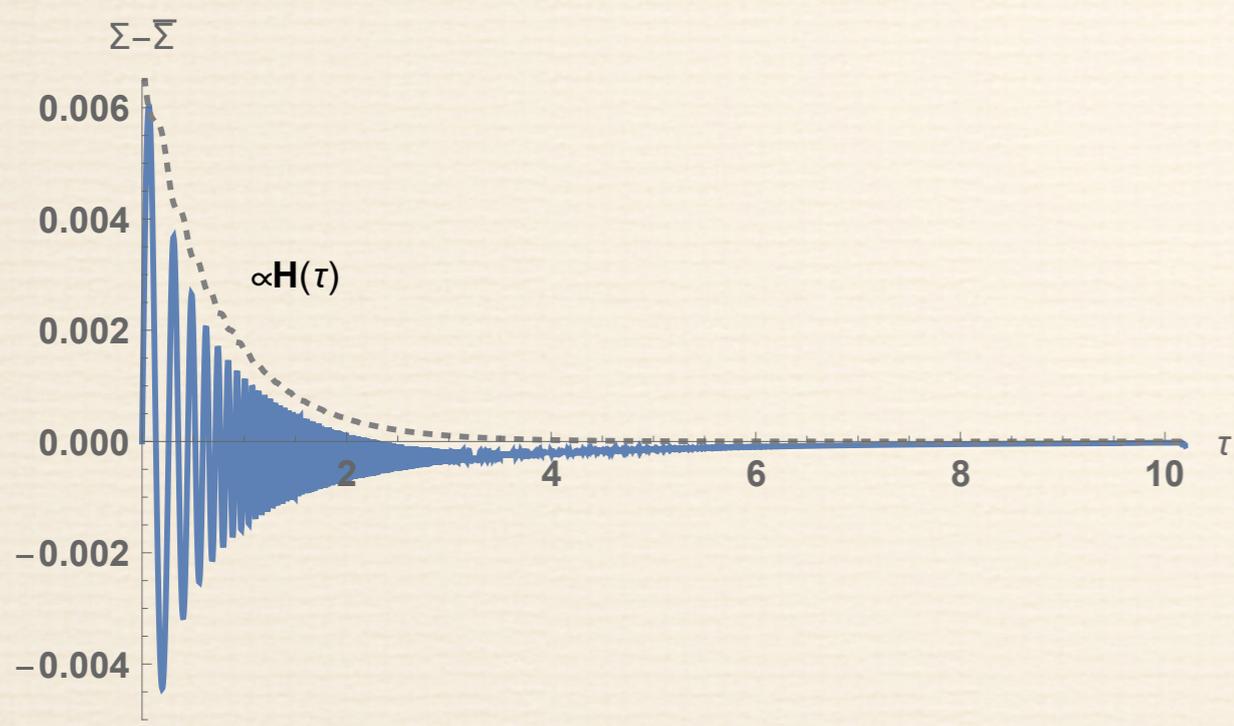
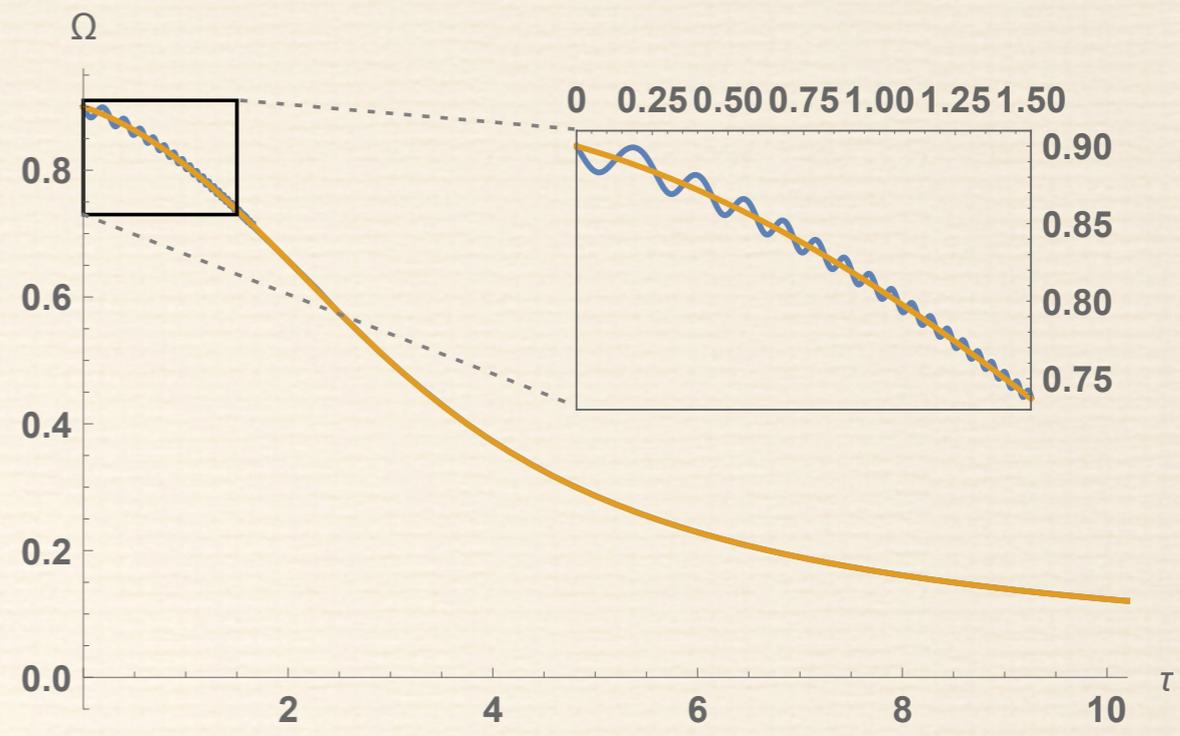
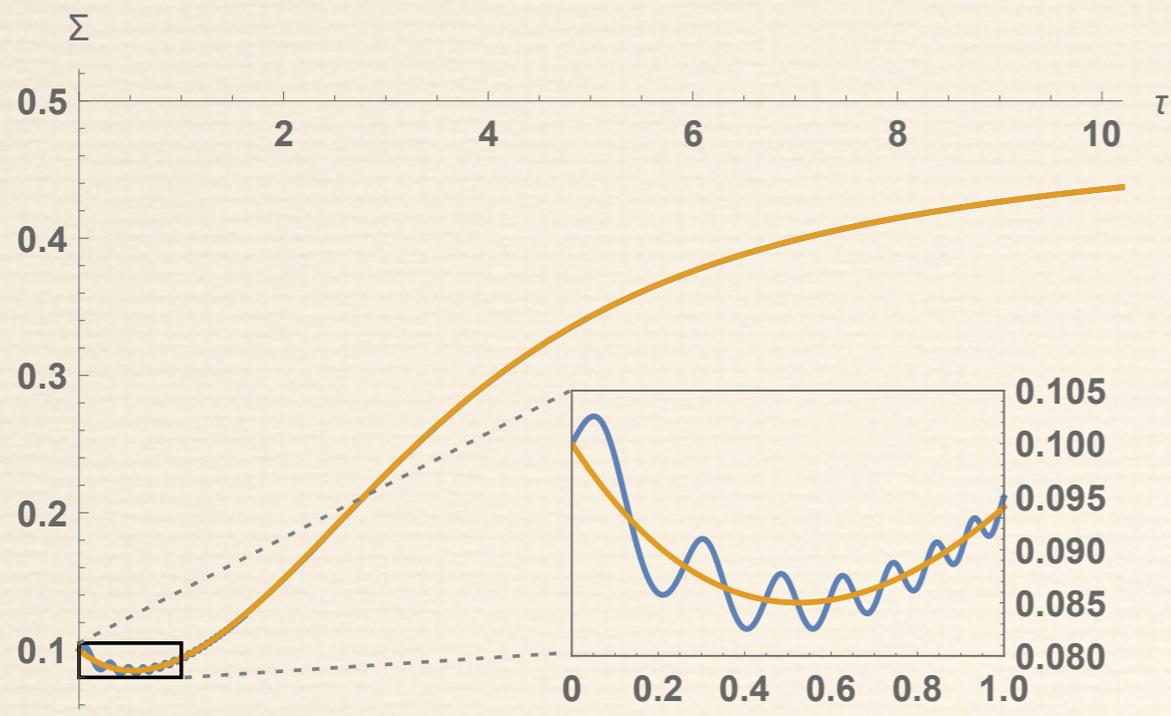
❖ **Theorem 2.** Assuming that the conjecture holds,

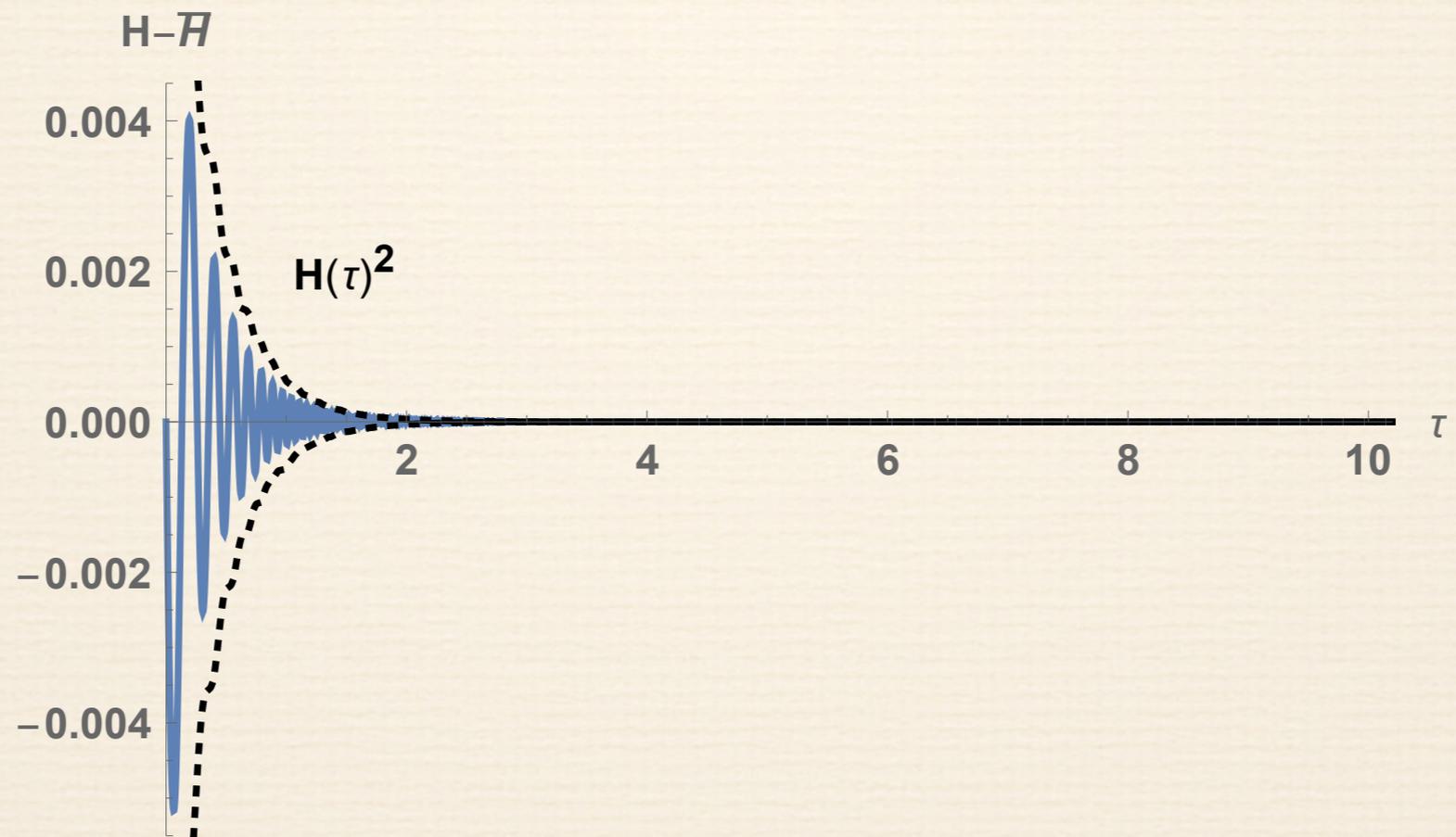
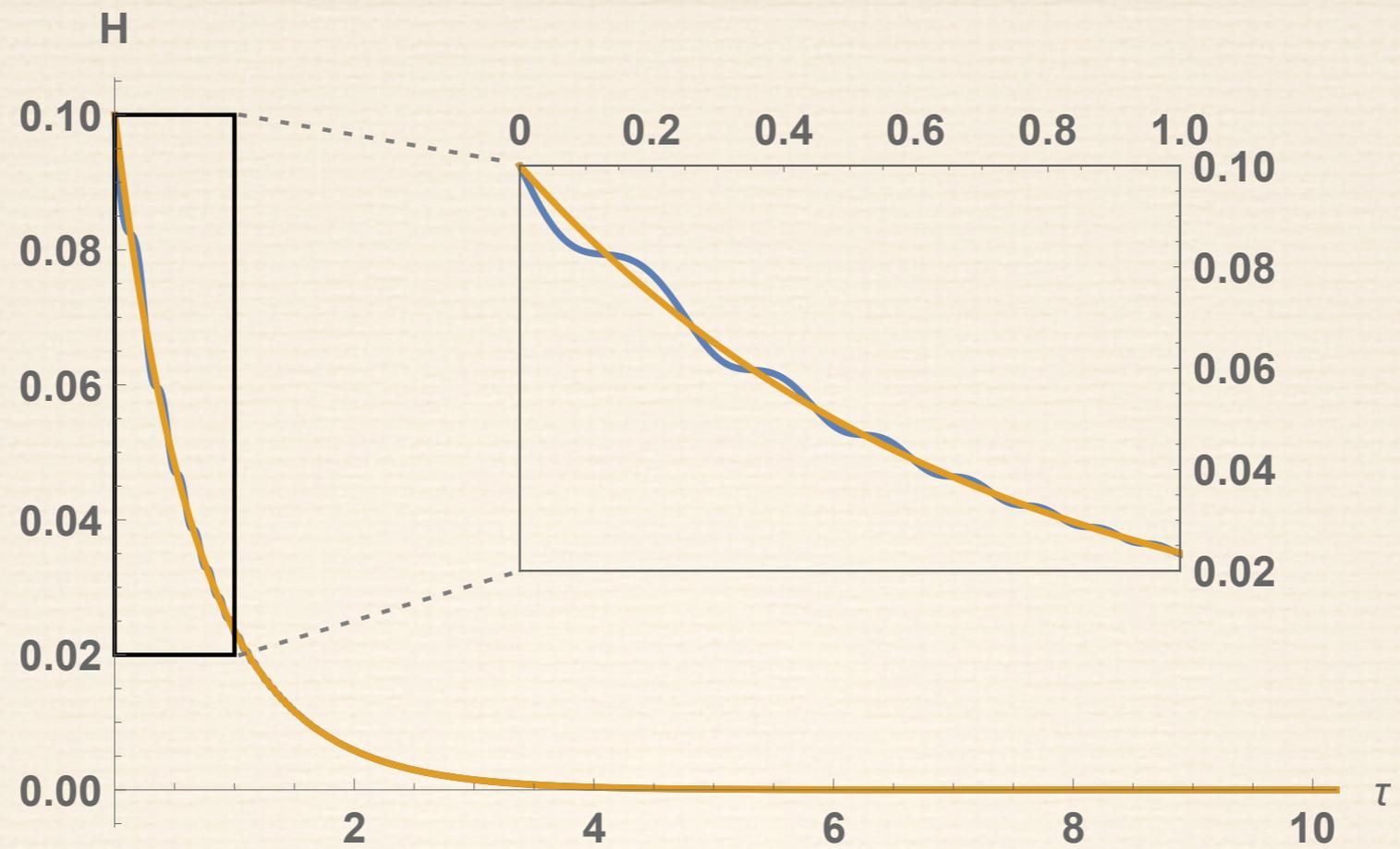
$$\mathbf{g} = - dt^2 + a(t)^2 dr^2 + b(t)^2 \mathbf{g}_{H^2}$$

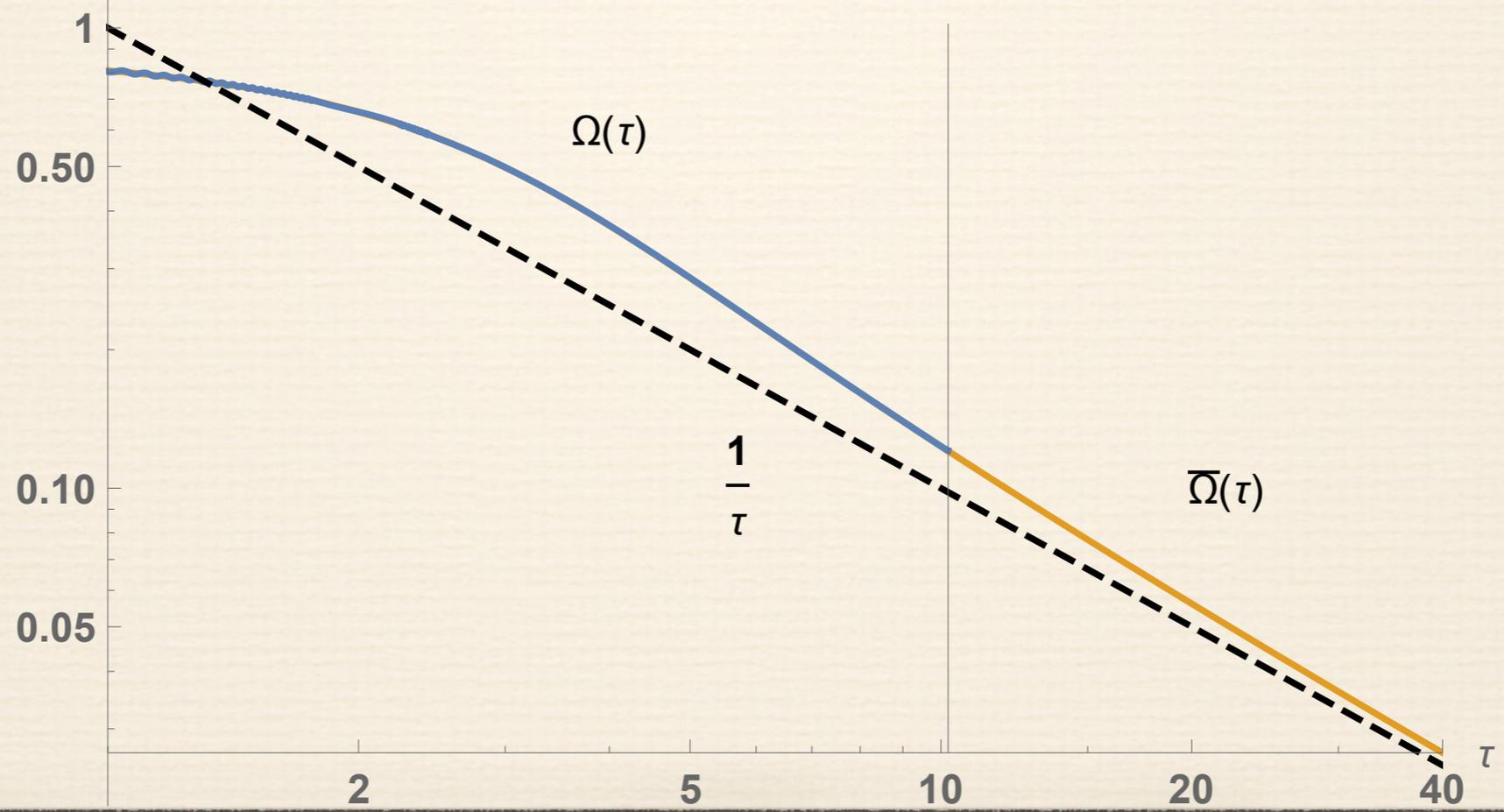
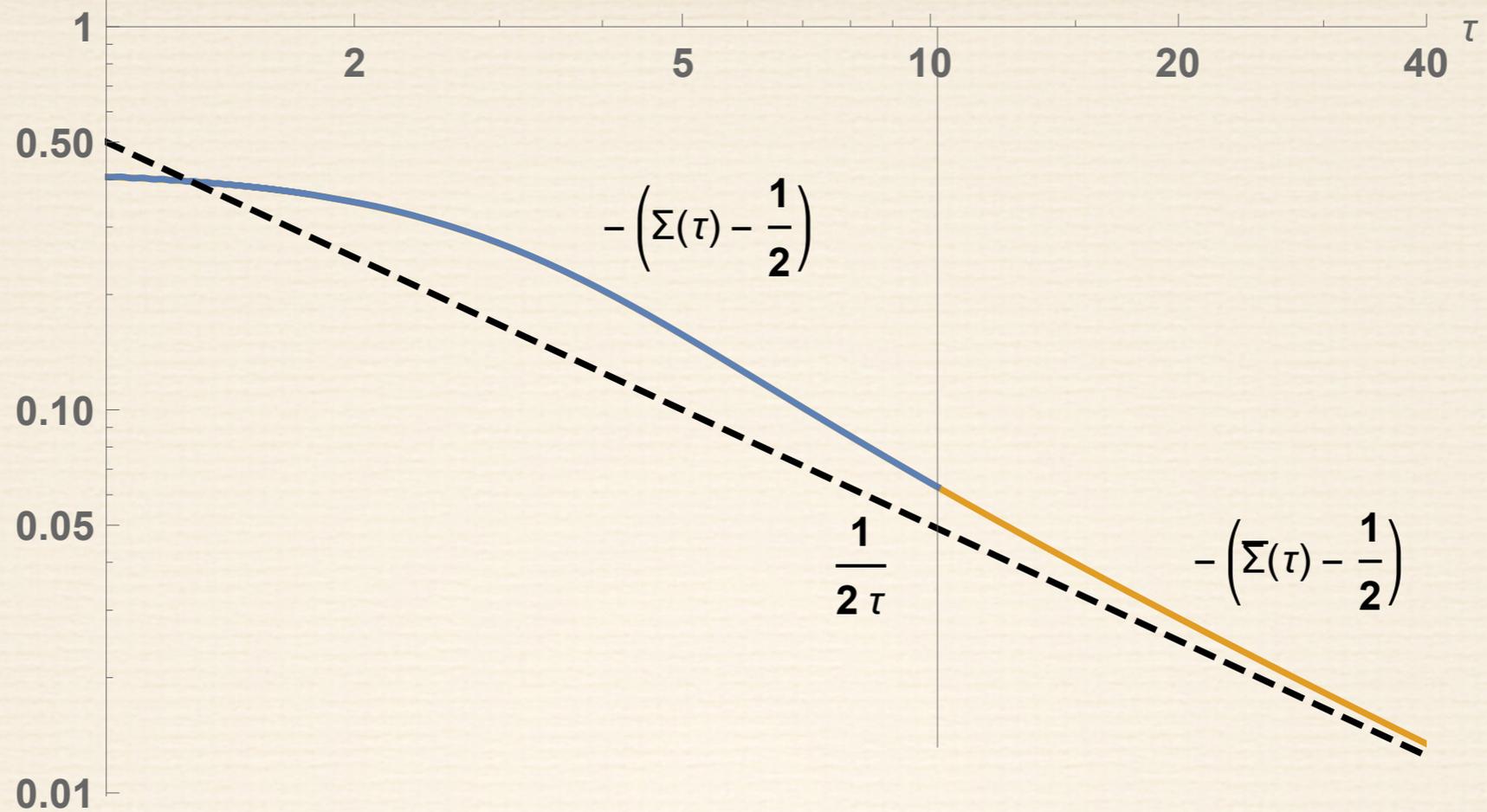
with $a(t) \approx c_1 \ln t$ and $b(t) \approx c_2 t$.

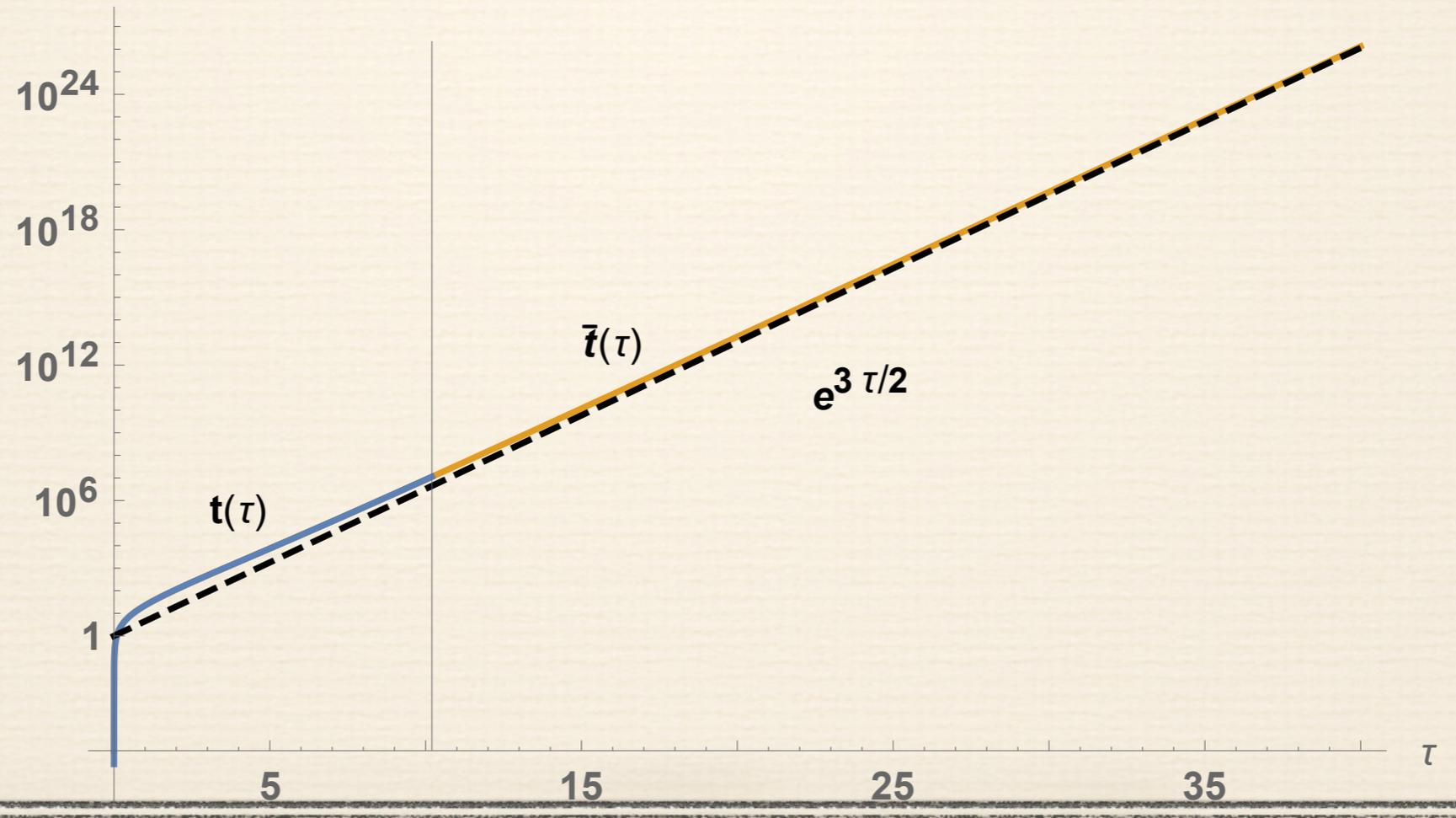
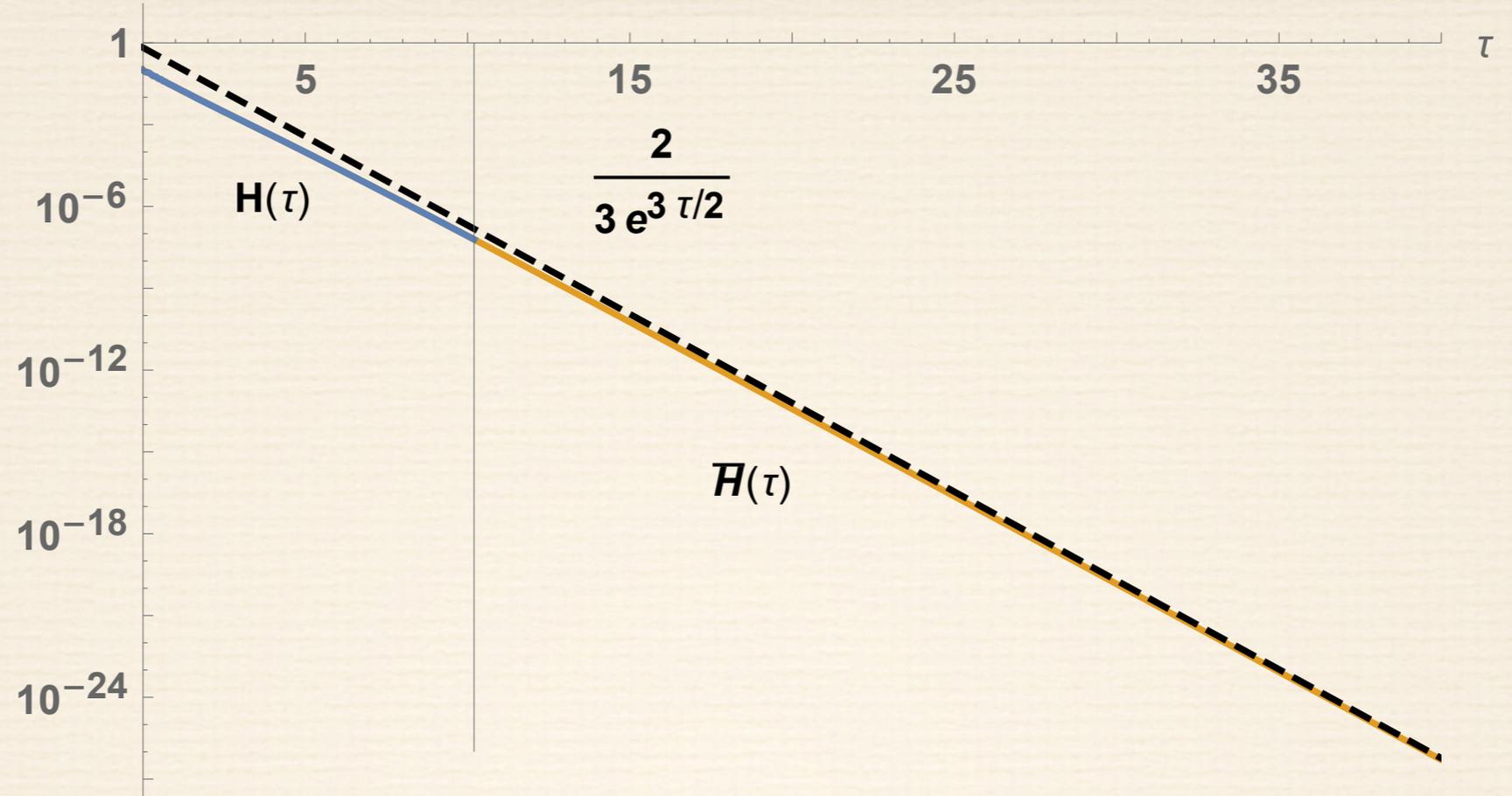
❖ Compare to vacuum solutions: $a(t) \approx c_1$, $b(t) \approx c_2 t$



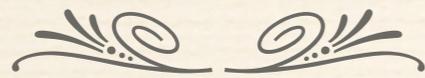




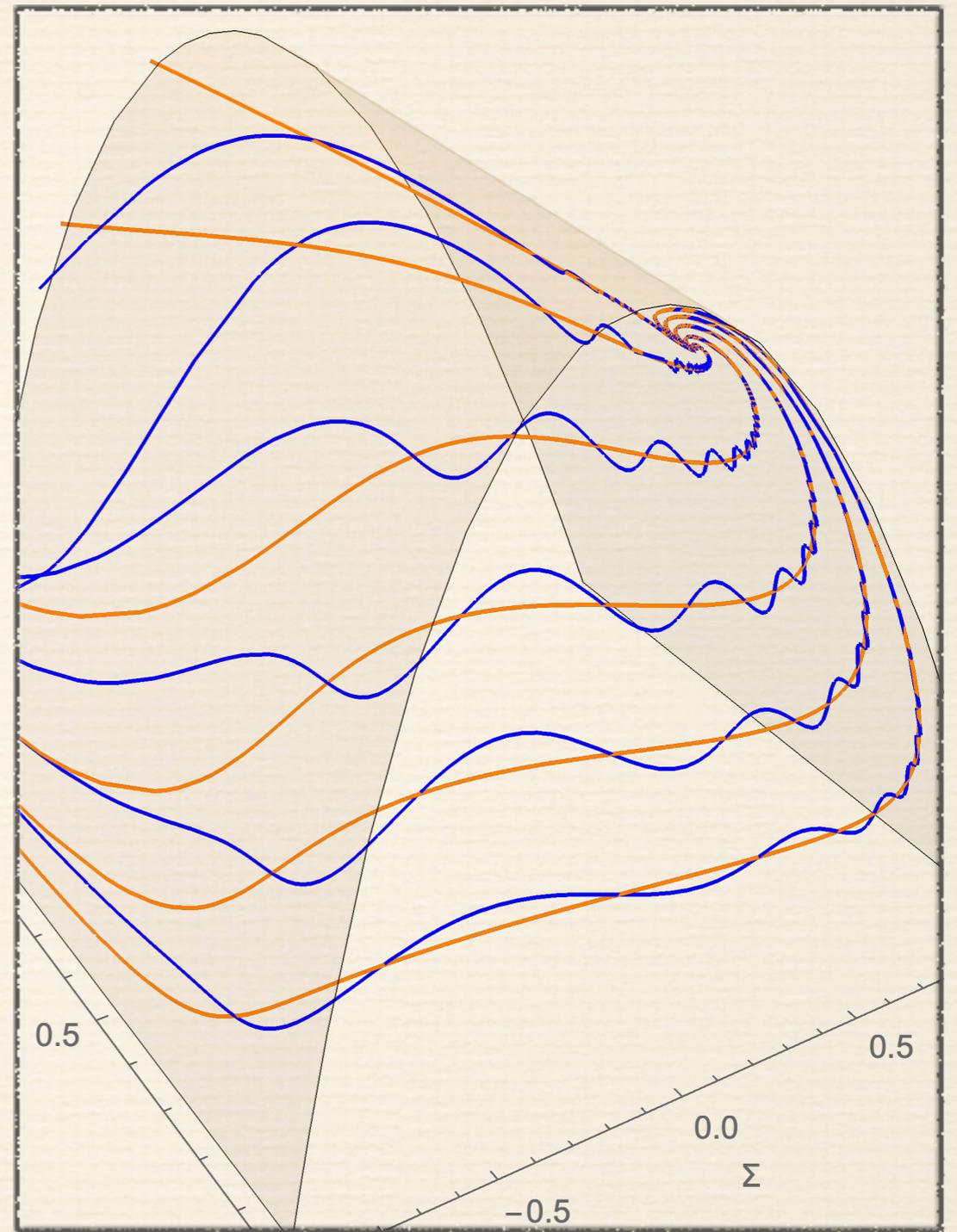




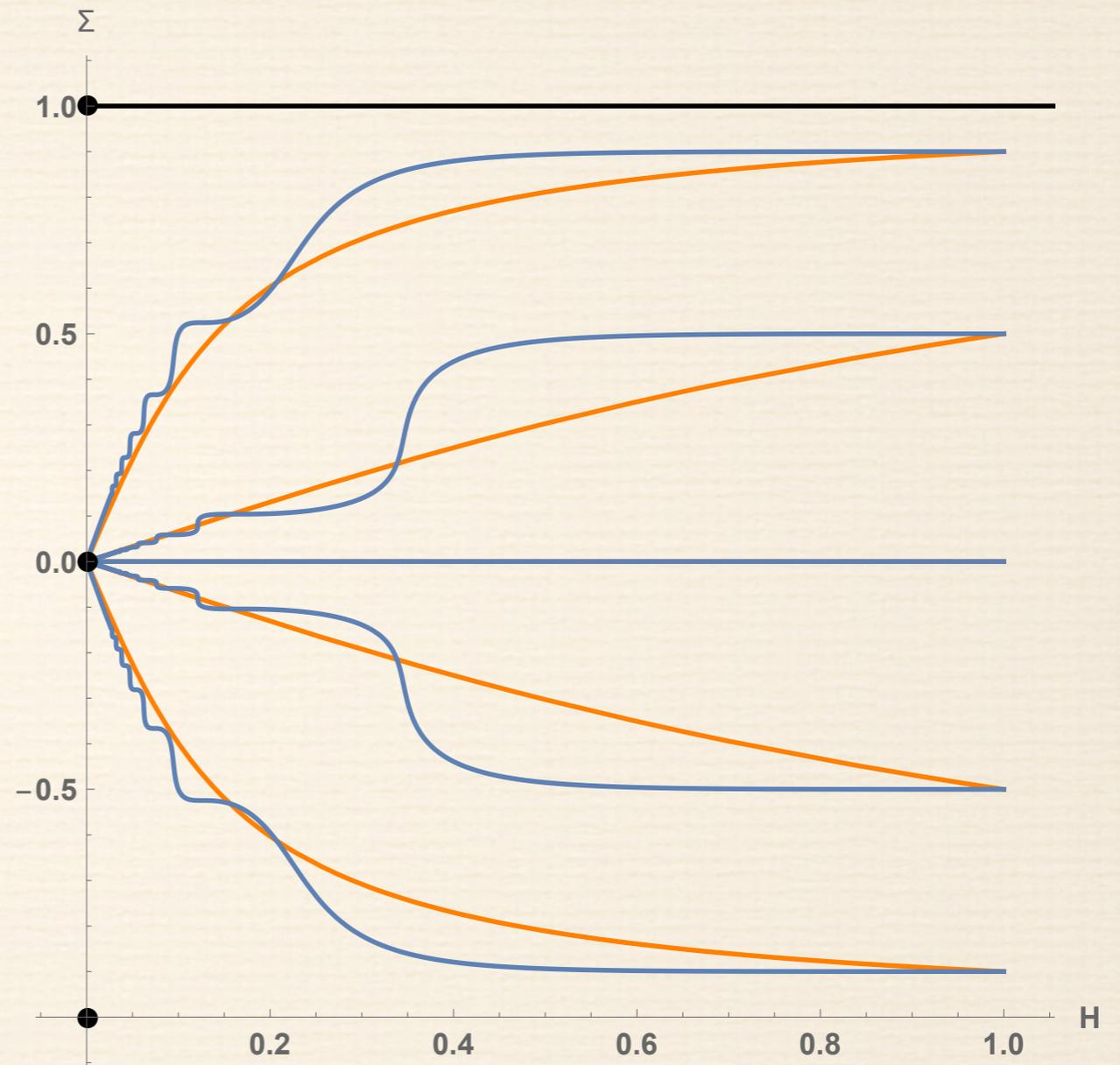
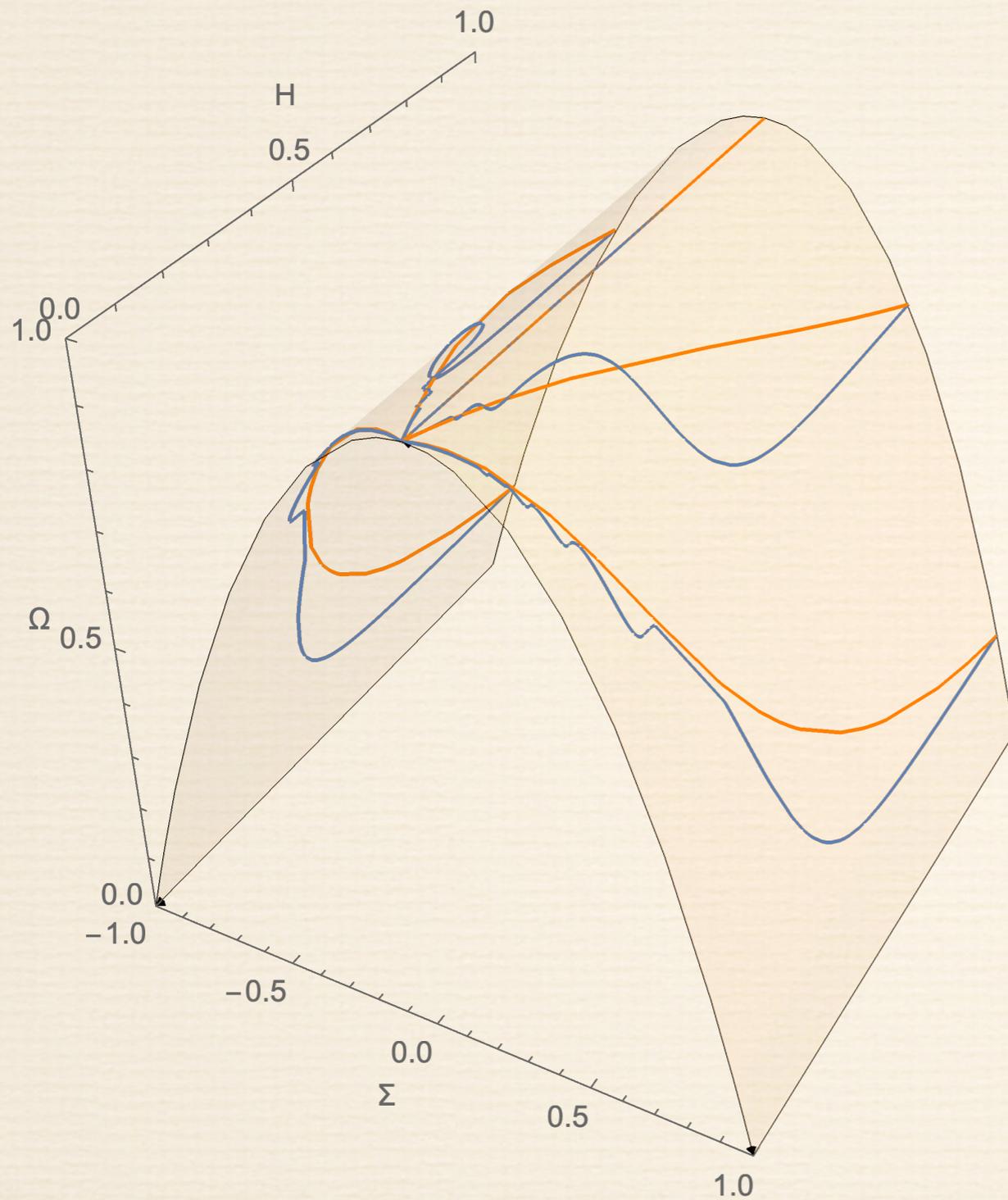
LRS Bianchi I & II



D Fajman, G Heißel

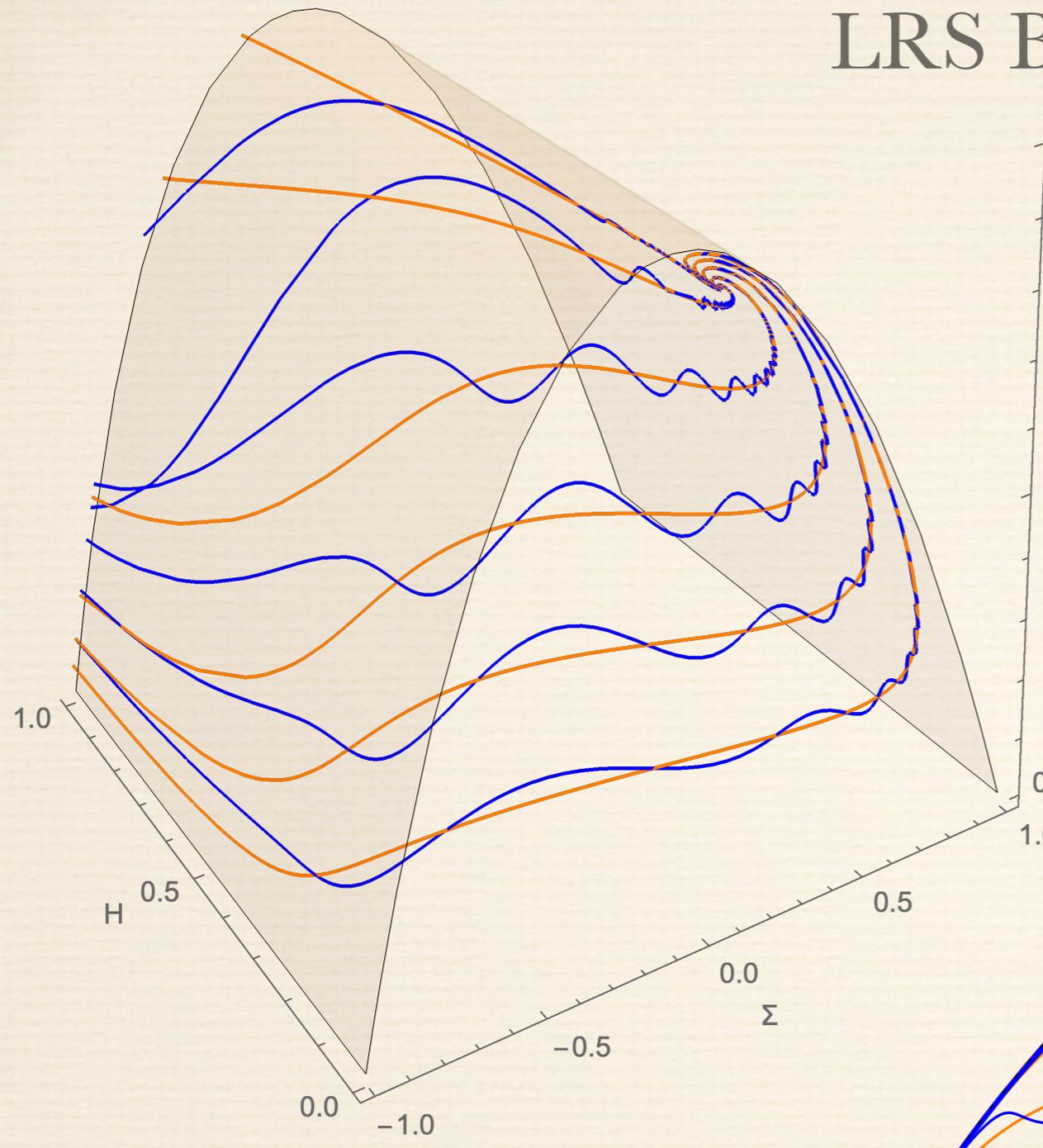


LRS Bianchi I

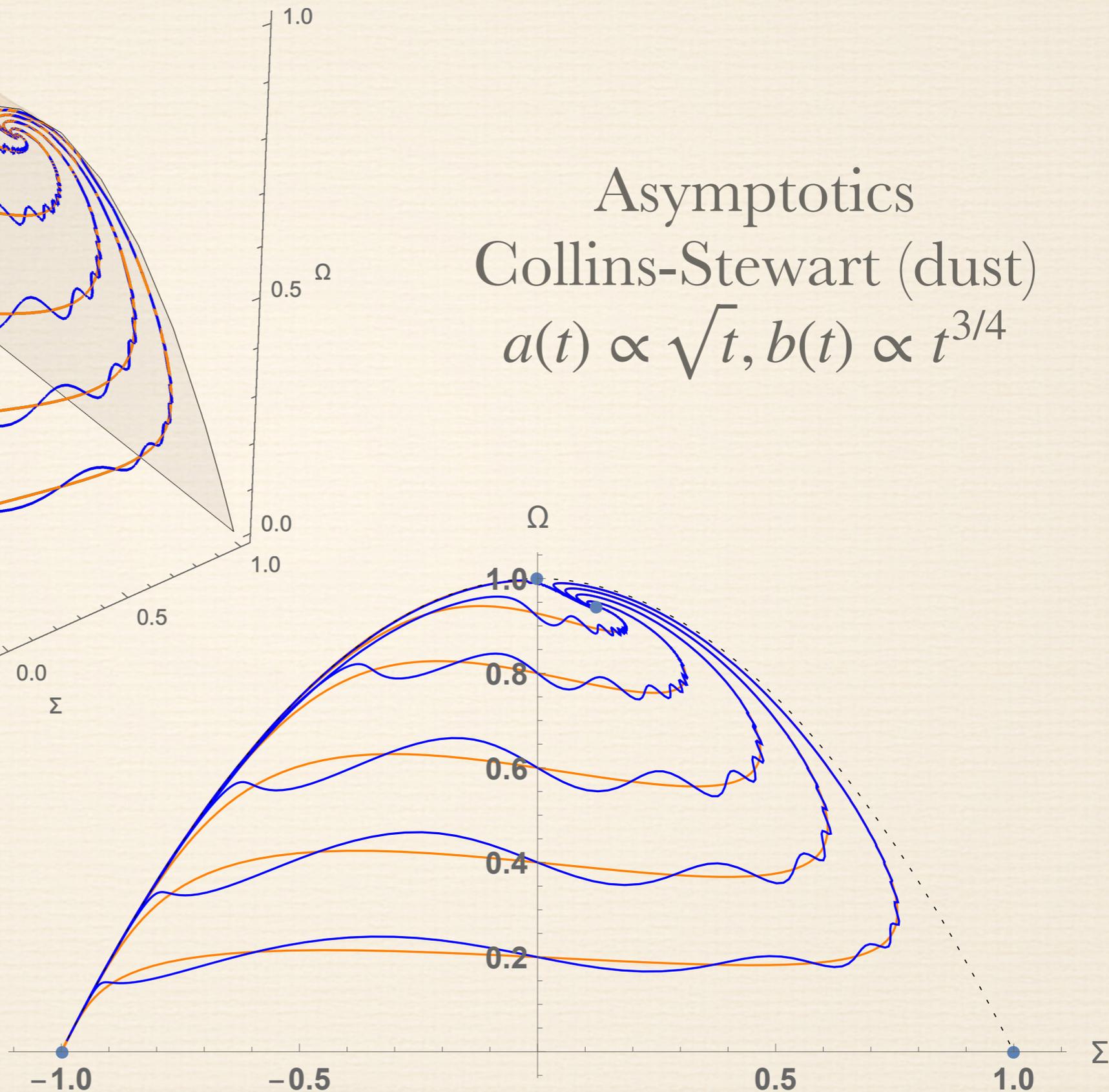


Asymptotics: Einstein-De-Sitter $a(t), b(t) \propto t^{2/3}$

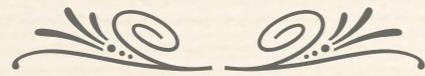
LRS Bianchi II



Asymptotics
Collins-Stewart (dust)
 $a(t) \propto \sqrt{t}, b(t) \propto t^{3/4}$



Thm: Averaging with time dependent perturbation



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m that we consider throughout this manuscript has the fo

$$\begin{bmatrix} \dot{H} \\ \dot{\mathbf{x}} \end{bmatrix} = H\mathbf{F}^1(\mathbf{x}, t) + H^2\mathbf{F}^{[2]}(\mathbf{x}, t) = H \begin{bmatrix} 0 \\ \mathbf{f}^1(\mathbf{x}, t) \end{bmatrix} + H^2 \begin{bmatrix} f^{[2]}(\mathbf{x}, t) \\ 0 \end{bmatrix}$$

$H(t)$ is positive, is strictly decreasing in t , and

$$\lim_{t \rightarrow \infty} H(t) = 0.$$

ow ready to introduce the statement of our main theorem:

.1. Suppose that $H = H(t) > 0$ is strictly decreasing in t ,

$$\lim_{t \rightarrow \infty} H(t) = 0.$$

fix any $\varepsilon > 0$ with $\varepsilon < H(0)$ and define $t_* > 0$ such that

$$\|\mathbf{f}^1\|_{L_{\mathbf{x},t}^\infty}, \|f^{[2]}\|_{L_{\mathbf{x},t}^\infty} < \infty,$$

$\mathbf{x}, t)$ is Lipschitz continuous and $f^{[2]}$ is continuous with res

lso, assume that \mathbf{f}^1 and $f^{[2]}$ are T -periodic for some $T >$

th $t = t_* + O(H(t_*)^{-\gamma})$ for some $\gamma \in (0, 1)$, we have

$$\mathbf{x}(t) - \mathbf{z}(t) = O(H(t_*)^{\min\{1, 2-2\gamma\}}),$$

he solution of the system (3.1) ^{ODEsystem} with the initial condition $\mathbf{x}(t_*)$ is the solution of the averaged equation

$$\dot{\mathbf{z}} = H(t_*)\bar{\mathbf{f}}^1(\mathbf{z}), \text{ for } t > t_*$$

ial condition $\mathbf{z}(t_*) = \mathbf{x}(t_*)$ where the average $\bar{\mathbf{f}}^1$ is defined

$$\bar{\mathbf{f}}^1(\mathbf{z}) = \frac{1}{T} \int_{t_*}^{t_*+T} \mathbf{f}^1(\mathbf{z}, s) ds.$$

$$\begin{bmatrix} \dot{H} \\ \dot{\mathbf{x}} \end{bmatrix} = H \begin{bmatrix} 0 \\ \mathbf{f}^1(\mathbf{x}, t) \end{bmatrix} + H^2 \begin{bmatrix} f^{[2]}(\mathbf{x}, t) \\ \mathbf{0} \end{bmatrix} \quad (3.1)$$

Theorem 3.1 (Local-in-time asymptotic). *Suppose that $H = H(t) > 0$ is strictly decreasing in t , and*

$$\lim_{t \rightarrow \infty} H(t) = 0.$$

Choose and fix any $\varepsilon > 0$ with $\varepsilon < H(0)$ and define $t_ > 0$ such that $\varepsilon = H(t_*)$. Suppose that*

$$\|\mathbf{f}^1\|_{L_{\mathbf{x},t}^\infty}, \|f^{[2]}\|_{L_{\mathbf{x},t}^\infty} < \infty,$$

and that $\mathbf{f}^1(\mathbf{x}, t)$ is Lipschitz continuous and $f^{[2]}$ is continuous with respect to \mathbf{x} for all $t \geq t_$. Also, assume that \mathbf{f}^1 and $f^{[2]}$ are T -periodic for some $T > 0$. Then for all $t > t_*$ with $t = t_* + O(H(t_*)^{-\gamma})$ for some $\gamma \in (0, 1)$, we have*

$$\mathbf{x}(t) - \mathbf{z}(t) = O(H(t_*)^{\min\{1, 2-2\gamma\}}),$$

where \mathbf{x} is the solution of the system (3.1) with the initial condition $\mathbf{x}(0) = \mathbf{x}_0$ and $\mathbf{z}(t)$ is the solution of the averaged equation

$$\dot{\mathbf{z}} = H(t_*)\bar{\mathbf{f}}^1(\mathbf{z}), \text{ for } t > t_*$$

with the initial condition $\mathbf{z}(t_) = \mathbf{x}(t_*)$ where the average $\bar{\mathbf{f}}^1$ is defined as*

$$\bar{\mathbf{f}}^1(\mathbf{z}) = \frac{1}{T} \int_{t_*}^{t_*+T} \mathbf{f}^1(\mathbf{z}, s) ds.$$

Theorem 3.2 (Global-in-time asymptotic). *Assume the same assumptions of Theorem 3.1. Then we have*

$$\lim_{\tau \rightarrow \infty} \|\mathbf{x}(\tau) - \mathbf{z}(\tau)\| = 0.$$

- ❖ Sufficient to prove LRS Bianchi I & II asymptotics
- ❖ Insufficient to prove LRS Bianchi III asymptotics

Thank you!